

INTERNATIONAL CONFERENCE ON AUTONOMOUS AGENTS & MULTIAGENT SYSTEMS

2015

4-8 May 2015 ISTANBUL CONGRESS CENTER

CONFERENCE PROGRAM

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EXHIBITIONS











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Contents



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Innovative Application Track Chairs Amal El Fallah Seghrouchni Milind Tambe

Robotics Track Chairs Alessandro Farinelli Gal Kaminka

Virtual Agents & Humans Track Chairs Catholijn Jonker Rui Prada

Blue Sky Ideas Track Chair Victor Lesser

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Jerome Lang Kate Larson **Yves Lesperance** Brian Logan Alessio Lomuscio Viviana Mascardi Nicolas Maudet Felipe Meneguzzi Emma Norling Simon Parsons Maria Polukarov Ariel Procaccia David Pynadath Alessandro Ricci Avi Rosenfeld Francesca Rossi Michael Rovatsos Iordi Sabater-Mir Sebastian Sardina David Sarne Sandip Sen Gita Sukthankar Matthew Taylor Wamberto Vasconcelos Rineke Verbrugge Shimon Whiteson Cees Witteveen Makoto Yokoo Roie Zivan

Innovative Applications Track

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Robotics Track

Noa Agmon Maria Gini Alexander Kleiner Daniele Nardi Paul Scerri Elizabeth Sklar Mohan Sridharan Manuela Veloso

Virtual Agents & Humans Track

Elisabeth Andre Ruth Aylett Timothy Bickmore Stefan Kopp Stacy Marsella Ana Paiva Catherine Pelachaud Mark Riedl Hannes Vilhjalmsson

Blue Sky Ideas Track

Ed Durfee Jeffrey S. Rosenschein Munindar Singh Liz Sonenberg



List of Workshops

- A2HC Agents Applied in Health Care
- ACAN Agent-based Complex Automated Negotiations
- ACySe Agents and CyberSecurity
- ADMI Agent & Data Mining Interaction
- ALA Adaptative and Learning Agents

AMEC/TADA – Agent-Mediated Electronic Commerce and Trading Agent Design and Analysis

- **ARMS** Autonomous Robots and Multirobot Systems
- ArgMAS Argumentation in Multi-Agent Systems
- CARE Collaborative Agents Research & Development
- **CAVE** Cognitive Agents for Virtual Environments
- **COIN** Coordination, Organisations, Institutions and Norms
- **CoopMAS** Cooperative Games in Multiagent Systems
- **COOS** Collaborative Online Organizations Workshop
- EMAS Engineering Multi-Agent Systems
- ESSEM Emotion and Sentiment in Social and Expressive Media

EXPLORE – Exploring Beyond the Worst Case in Computational Social Choice

- HAIDM Human–Agent Interaction Design and Models
- IDEAS Issues with Deployment of Emerging Agent-based Systems
- LAMAS Logical Aspects of Multi-Agent Systems
- MABS Multi-Agent-Based Simulation
- MassiveMAS Autonomous Agents and Multi-Agent Systems at Scale



- **MFSC** Multiagent Foundations of Social Computing
- **MSDM** Multiagent Sequential Decision Making Under Uncertainty
- **ODMMRC** On-line Decision Making in Multi-Robot Coordination
- **OptMAS** Optimisation in Multi-Agent Systems
- **WEIN** Workshop on Emergent Intelligence on Networked Agents



List of Tutorials

T1. Strategic Voting and Strategic Candidacy in Multi-Agent Systems – Maria Polukarov, Svetlana Obraztsova, Zinovi Rabinovich

T2. Complex Event Recognition in Multi-Agent Systems – Alexander Artikis, Matthias Weidlich

T3. Decentralized Multiagent Systems – Amit K. Chopra, Munindar P. Singh

T4. Norm Synthesis in Normative Multi-Agent System – Maite Lopez-Sanchez

T5. Principles of Automated Negotiation – Shaheen Fatima, Sarit Kraus, Michael Wooldridge

T6. Multi-Agent Oriented Programming – Olivier Boissier, Jomi Hübner, Alessandro Ricci, Jaime Simão Sichman

T7. Modeling and Simulation using Agents in Cell-Spaces -

Gabriel A. Wainer

T8. Truth-Revealing Social Choice – Toby Walsh, Lirong Xia, Leandro Soriano Marcolino



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Programme At-a-Glance

Monday 4 May 2015	
08.30 - 10.30	Workshops: ADMI, AMEC/TADA, ARMS, COIN, COOS, EXPLORE, HAIDM, IDEAS, LAMAS Tutorials: T2, T3
10.30 - 11.00	Coffee Break
11.00 - 13.00	Workshops: ADMI, AMEC/TADA, ARMS, COIN, COOS, EXPLORE, HAIDM, IDEAS, LAMAS Tutorials: T3, T7
13.00 - 14.00	Lunch Break
14.00 - 16.00	Workshops: ADMI, AMEC/TADA, ARMS, CARE, COIN, HAIDM, LAMAS, MFSC Tutorials: T1, T6
16.00 - 16.30	Coffee Break
16.30 - 18.30	Workshops: ADMI, AMEC/TADA, ARMS, CARE, COIN, HAIDM, LAMAS, MFSC Tutorials: T6, T8

Please see page 12 for the detailed programme with the associated rooms.



Programme At-a-Glance

Tuesday 5 May 2015	
08.30 - 10.30	Workshops: ACAN, ACySe, ALA, CoopMAS, EMAS, ES- SEM, MABS, MassiveMAS, OptMAS Tutorials: T5 Doctoral Symposium
10.30 - 11.00	Coffee Break
11.00 - 13.00	Workshops: ACAN, ACySe, ALA, CoopMAS, EMAS, ES- SEM, MABS, MassiveMAS, OptMAS Tutorials: T5 Doctoral Symposium
13.00 - 14.00	Lunch Break
14.00 - 16.00	Workshops: A2HC, ACAN, ACySe, ALA, CoopMAS, EMAS, ESSEM, MABS, MassiveMAS, MSDM, OptMAS Tutorials: T4 Doctoral Symposium
16.00 - 16.30	Coffee Break
16.30 - 18.30	Workshops: A2HC, ACAN, ACySe, ALA, CoopMAS, EMAS, ESSEM, MABS, MassiveMAS, MSDM, OptMAS Doctoral Symposium
19.00 - 21.30	Welcome Reception

Please see page 14 for the detailed programme with the associated rooms.



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Programme At-a-Glance

	Wednesday 6 May 2015
08.45 - 09.00	Conference Opening
	Keynote: David Harel
10.00 - 11.00	Coffee, Posters
11.00 - 12.30	Game Theory I Social Choice I Learning I Logic I Bio-inspired Approaches
12.30 - 14.30	Lunch Break, Posters
14.30 - 16.00	Game Theory II Cooperation Agent Societies Applications I Virtual Agents and Humans I
16.00 - 16.30	Coffee, Demonstrations
16.30 - 17.50	Discussion Panel

Please see page 17 for the detailed programme with the associated rooms.



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Programme At-a-Glance

	Thursday 7 May 2015
	Keynote: Nina Balcan
10.00 - 11.00	Coffee, Posters
11.00 - 12.30	Game Theory III Social Choice II Learning II Applications II Robotics I
12.30 - 14.30	Lunch Break, Posters
14.30 - 16.00	Game Theory IV Logic II Engineering Agent-Based Systems Applications III Planning I
16.00 - 16.30	Coffee, Demonstrations
16.30 - 17.15	Blue Sky Ideas Hedonic Games Planning II Applications IV Robotics II
17.15 - 18.15	IFAAMAS Victor Lesser Distinguished Dissertation Award Talk: Yair Zick
19.30 - 23.30	Gala Dinner

Please see page 31 for the detailed programme with the associated rooms.



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Programme At-a-Glance

	Friday 8 May 2015
09.00 - 10.00	ACM/SIGAI Autonomous Agents Award Talk: Catherine Pelachaud
10.00 - 11.00	Coffee, Demonstrations, Posters
11.00 - 12.30	Game Theory V Social Choice III Logic III Virtual Agents and Humans II Robotics III
12.30 - 14.30	Lunch and Community Meeting

All paper authors and demonstration presenters are welcome to present during the Friday coffee break session, subject to space availability on a first come, first served basis.

Please see page 47 for the detailed programme with the associated rooms.



Detailed Programme

Monday 4 May 2015

Monday 4 May / Workshops — Morning 08.30 - 10.30 / 11.00 - 13.00

ADMI — Agent & Data Mining Interaction *Room: B3.21*

AMEC/TADA — Agent-Mediated Electronic Commerce and Trading Agent Design and Analysis *Room: B3.20*

Affiliated with AMEC/TADA is the Trading Agents Competition (TAC).

ARMS — Autonomous Robots and Multirobot Systems *Room: B3.22*

COIN — Coordination, Organisations, Institutions and Norms *Room: B3.61*

COOS — Collaborative Online Organizations Workshop *Room: B3.85*

EXPLORE — Exploring Beyond the Worst Case in Computational Social Choice *Room: B3.70*

HAIDM — Human-Agent Interaction Design and Models *Room: B3.87*

IDEAS — Issues with Deployment of Emerging Agent-based Systems *Room: B3.67*

LAMAS — Logical Aspects of Multi-Agent Systems *Room: B3.88*

Monday 4 May / Tutorials — Morning 08.30 – 10.30 / 11.00 – 13.00

T2 — Complex Event Recognition in Multi-Agent Systems (08.30 – 10.30) *Room: B3.86*

T3 — Decentralized Multiagent Systems *Room: B3.60*



T7 — Modeling and Simulation using Agents in Cell-Spaces (11.00 – 13.00) *Room: B3.86*

Monday 4 May / Workshops — Afternoon 14.00 – 16.00 / 16.30 – 18.30

ADMI — Agent & Data Mining Interaction *Room: B3.21*

AMEC/TADA — Agent-Mediated Electronic Commerce and Trading Agent Design and Analysis *Room: B3.20*

ARMS — Autonomous Robots and Multirobot Systems *Room: B3.22*

CARE — Collaborative Agents – Research & Development *Room: B3.70*

COIN — Coordination, Organisations, Institutions and Norms *Room: B3.61*

HAIDM — Human–Agent Interaction Design and Models *Room: B3.87*

LAMAS — Logical Aspects of Multi-Agent Systems *Room: B3.88*

MFSC — Multiagent Foundations of Social Computing *Room: B3.85*

Monday 4 May / Tutorials — Afternoon 14.00 – 16.00 / 16.30 – 18.30

T1 — Strategic Voting and Strategic Candidacy in Multi-Agent Systems (14.00 – 16.00) *Room: B3.60*

T6 — Multi-Agent Oriented Programming *Room: B3.86*

T8 — Truth-Revealing Social Choice (16.30 – 18.30) *Room: B3.60*



Tuesday 5 May 2015

Tuesday 5 May — Workshops / Morning 08.30 – 10.30 / 11.00 – 13.00

ACAN — Agent-based Complex Automated Negotiations *Room: B3.86*

Affiliated with ACAN is the Automated Negotiating Agents Competition (ANAC).

ACySe — Agents and CyberSecurity *Room: B3.67*

ALA — Adaptative and Learning Agents *Room: B3.22*

CoopMAS — Cooperative Games in Multiagent Systems *Room: B3.88*

COOS — Collaborative Online Organizations Workshop *Room: B3.85*

EMAS — Engineering Multi-Agent Systems *Room: B3.20*

ESSEM — Emotion and Sentiment in Social and Expressive Media *Room: B3.85*

EXPLORE — Exploring Beyond the Worst Case in Computational Social Choice *Room: B3.70*

IDEAS — Issues with Deployment of Emerging Agent-based Systems *Room: B3.67*

MABS — Multi-Agent-Based Simulation *Room: B3.70*

MassiveMAS — Autonomous Agents and Multi-Agent Systems at Scale *Room: B3.21*

OptMAS — Optimisation in Multi-Agent Systems *Room: B3.87*



Tuesday 5 May / Tutorials — Morning 08.30 - 10.30 / 11.00 - 13.00

T5 — Principles of Automated Negotiation *Room: B3.60*

<u>Tuesday 5 May — Workshops / Afternoon</u> 14.00 – 16.00 / 16.30 – 18.30

A2HC — Agents Applied in Health Care *Room: B3.82*

ACAN — Agent-based Complex Automated Negotiations *Room: B3.86*

ACySe — Agents and CyberSecurity *Room: B3.67*

ALA — Adaptative and Learning Agents *Room: B3.22*

CoopMAS — Cooperative Games in Multiagent Systems *Room: B3.88*

EMAS — Engineering Multi-Agent Systems *Room: B3.20*

ESSEM — Emotion and Sentiment in Social and Expressive Media *Room: B3.85*

MABS — Multi-Agent-Based Simulation *Room: B3.70*

MassiveMAS — Autonomous Agents and Multi-Agent Systems at Scale *Room: B3.21*

MSDM — Multiagent Sequential Decision Making Under Uncertainty *Room: B3.67*

OptMAS — Optimisation in Multi-Agent Systems *Room: B3.87*

Tuesday 5 May / Tutorials — Afternoon 14.00 – 16.00

T4 — Norm Synthesis in Normative Multi-Agent System *Room: B3.60*



Tuesday 5 May — Doctoral Symposium — Full day 08.45 – 10.30 / 11.00 – 12.00 / 14.00 – 16.00 / 16.30 – 17.35

Room: B3.61

- 08.45 09.30 Welcome and introductions
- 09.30 10.30 Career interview

with Gal Kaminka and Kate Larson

- 10.30 11.00 Coffee
- 11.00 12.00 Presentations Session I
- 12.00 14.00 Lunch
- 14.00 15.00 Panel discussion
- 15.00 16.00 Presentations Session II
- 16.00 16.30 Coffee
- 16.30 17.35 Poster session

Tuesday 5 May — Evening

19.00 - 21.30

Welcome Reception

The welcome reception will take place at Boğaziçi University. (Please see page 62 for details.)



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Wednesday 6 May 2015

Wednesday 6 May — Morning

08.45 – 09.00 Conference Opening *Room: Üsküdar 2*

<u>Wednesday 6 May — Keynote — A</u> 09.00 – 10.00

On the Full Organism Challenge: Or, Can we Computerize an Elephant? David Harel Room: Üsküdar 2 Chair: Rafael Bordini

Wednesday 6 May — Coffee and Posters

Indicated poster and demonstrations slots are suggestions only, as there will be both posters and demos available in all breaks. Posters will also be presented during the poster sessions by authors of full length papers who have chosen to do so.

10.00 – 11.00 Poster Session 1 *Room: Foyer*

W-01: Ex post Efficiency of Random Assignments Haris Aziz, Simon Mackenzie, Lirong Xia, Chun Ye

W-02: Voter Dissatisfaction in Committee Elections *Dorothea Baumeister, Sophie Dennisen*

W-03: How Hard is Bribery in Party Based Elections? Yongjie Yang, Yash Raj Shrestha, Jiong Guo

W-04: How Hard is Control in Multi-Peaked Elections: a Parameterized Study

Yongjie Yang, Jiong Guo

W-05: Profit Maximizing Prior-free Multi-unit Procurement Auctions with Capacitated Sellers

Arupratan Ray, Debmalya Mandal, Yadati Narahari

W-06: Spiteful Bidding in the Dollar Auction

Marcin Waniek, Agata Niescieruk, Tomasz Michalak, Talal Rahwan



W-07: Learning Payoffs in Large Symmetric Games Bryce Wiedenbeck, Michael P. Wellman

W-08: Selecting Robust Strategies Based on Abstracted Game Models Oscar Veliz, Christopher Kiekintveld

W-09: Cascade Model with Contextual Externalities and Bounded User Memory for Sponsored Search Auctions

Nicola Gatti, Marco Rocco, Paolo Serafino, Carmine Ventre

W-10: Game-Theoretic Algorithms for Optimal Network Security Hardening Using Attack Graphs

Karel Durkota, Viliam Lisy, Christofer Kiekintveld, Branislav Bosansky

W-11: New Mechanism for Reservation in Cloud Computing

Changjun Wang, Weidong Ma, Tao Qin, Feidiao Yang, Tie-Yan Liu, Xujin Chen, Xiaodong Hu

W-12: Near Optimal Strategies for Targeted Marketing in Social Networks

Ramakumar Pasumarthi, Ramasuri Narayanam, Balaraman Ravindran

W-13: Applying the Synergy Graph Model to Human Basketball

Somchaya Liemhetcharat, Yicheng Luo

W-14: Now, Later, or Both: a Closed-Form Optimal Decision for a Risk-Averse Buyer

Jasper Hoogland, Mathijs De Weerdt, Han La Poutréé

W-15: Multiagent Fair Optimization with Lorenz Dominance

Lucie Galand, Thibaut Lust

W-16: Defender Strategies In Domains Involving Frequent Adversary Interaction

Fei Fang, Peter Stone, Milind Tambe

W-17: Bounded Rationality of Restricted Turing Machines Lijie Chen, Pingzhong Tang

W-18: Empirical Analysis of Reputation-aware Task Delegation by Humans from a Multi-agent Game

Han Yu, Han Lin, Su Fang Lim, Jun Lin, Zhiqi Shen, Chunyan Miao

W-19: Quality and Budget Aware Task Allocation for Spatial Crowd-sourcing

Han Yu, Chunyan Miao, Zhiqi Shen, Cyril Leung



W-20: A Multi-phase Approach for Improving Information Diffusion in Social Networks

Swapnil Dhamal, Prabuchandran K. J., Yadati Narahari

W-21: Real-time Bidding based Vehicle Sharing

Yinlam Chow, Jia Yuan Yu

W-22: A Market for Reliability for Electricity Scheduling in Developing World Microgrids

Daniel Strawser, Wardah Inam, Brian Williams

W-23: Towards Social Power Intelligent Agents

Gonçalo Duarte Garcia Pereira, Rui Prada, Pedro A. Santos

W-24: Exploring Social Power Intelligent Behavior

Gonçalo Duarte Garcia Pereira, Rui Prada, Pedro A. Santos

W-25: Coping with Moral Emotions

Cristina Battaglino, Rossana Damiano

W-26: A Dancing Virtual Agent to Evoke Human Emotions

Deborah Richards, Jon Cedric Roxas, Ayse Bilgin, Nader Hanna

W-27: Laughing with a Virtual Agent

Florian Pecune, Maurizio Mancini, Beatrice Biancardi, Giovanna Varni, Yu Ding, Catherine Pelachaud, Gualtiero Volpe, Antonio Camurri

W-28: Discovery, Evaluation, and Exploration of Human Supplied Options and Constraints

Jesse Rosalia, Guliz Tokadli, Charles L. Isbell Jr., Andrea Thomaz, Karen M. Feigh

W-29: Heuristic Collective Learning for Efficient and Robust Emergence of Social Norms

Hao Jianye, Jun Sun, Dongping Huang, Yi Cai, Chao Yu

W-30: The Efficient Interaction of Costly Punishment and Commitment *The Anh Han, Tom Lenaerts*

W-31: Towards Planning Uncertain Commitment Protocols

Felipe Meneguzzi, Pankaj R Telang, Neil Yorke-Smith

W-32: Social Contexts and Social Pragmatics

Matteo Baldoni, Cristina Baroglio, Amit K. Chopra, Munindar P. Singh

W-33: Convention Emergence and Influence in Dynamic Topologies James Marchant, Nathan Griffiths, Matthew Leeke



W-34: Norm Establishment Constrained by Limited Resources

Samhar Mahmoud, Simon Miles, Adel Taweel, Brendan Delaney, Michael Luck

W-35: SMT-based Bounded Model Checking for Weighted Interpreted Systems and for Weighted Epistemic ECTL

Agnieszka M. Zbrzezny, Bozena Wozna-Szczesniak, Andrzej Zbrzezny

W-36: Verification of Multi-Agent Systems via SDD-based Model Checking

Alessio Lomuscio, Hugo Paquet

W-37: A Model for Collaborative Runtime Verification

Bas Testerink, Nils Bulling, Mehdi Dastani

W-38: Symbolic Model-checking for Resource-Bounded ATL

Natasha Alechina, Brian Logan, Hoang Nga Nguyen, Franco Raimondi, Leonardo Mostarda

W-39: Strategies for Truth Discovery under Resource Constraints Anthony Etuk, Timothy J. Norman, Nir Oren, Murat Sensoy

W-40: Towards Agent-Based Simulation of Maritime Customs *F. Jordan Srour, Neil Yorke-Smith*

W-41: Calibration of Multi-Agent Simulations through a Participatory Experiment

Kévin Darty, Julien Saunier, Nicolas Sabouret

W-42: Validating Business Requirements Using MAS Analysis Models

Nektarios Mitakides, Nikolaos Spanoudakis, Pavlos Delias

W-43: Emigration or Tax Evasion?

Nuno Trindade Magessi, Luis Antunes

W-44: Computer Aided Tax Evasion Policy Analysis: Directed Search using Autonomous Agents

Jacob B. Rosen, Erik Hemberg, Geoff Warner, Sanith Wijesinghe, Una-May O'Reilly

W-45: Reducing diffusion time in attitude diffusion models through agenda setting.

Kiran Lakkaraju

W-46: Multi-Objective Multiagent Credit Assignment in NSGA-II Using Difference Evaluations

Logan Yliniemi, Drew Wilson, Kagan Tumer



W-47: Multi-Scale Reward Shaping via an Off-Policy Ensemble Anna Harutyunyan, Tim Brys, Peter Vrancx, Ann Nowe

W-48: Trajectory Sampling Value Iteration: Improved Dyna Search for MDPs

Yicheng Zhou, Quan Liu, Qiming Fu, Zongzhang Zhang

W-49: P-MARL: Prediction-Based Multi-Agent Reinforcement Learning for Non-Stationary Environments

Andrei Marinescu, Ivana Dusparic, Adam Taylor, Vinny Cahill, Siobhán Clarke

W-50: A Hybrid Evolutionary and Multiagent Reinforcement Learning Approach to Accelerate the Computation of Traffic Assignment

Ana L.C. Bazzan, Camelia Chira

W-51: A Continuous Negotiation Based Model for Traffic Regulation at an Intersection

Matthis Gaciarz, Samir Aknine, Neila Bhouri

W-52: Social Network Driven Traffic Decongestion Using Near Time Forecasting

Deepika Pathania, Kamalakar Karlapalem

W-53: Incremental Knowledge Acquisition with Selective Active Learning

Batbold Myagmarjav, Mohan Sridharan

W-54: An Efficient Knowledge Transfer Solution to a Novel SMDP Formalization of a Broker's Decision Problem

Rodrigue T. Kuate, Maria Chli, Hai H. Wang

W-55: Nonparametric Bayesian Learning of Other Agents' Policies in Interactive POMDPs

Alessandro Panella, Piotr J. Gmytrasiewicz

W-56: Improved Planning for Infinite-Horizon Interactive POMDPs using Probabilistic Inference

Xia Qu, Prashant Doshi

W-57: The "Favors Game": A Framework to Study the Emergence of Cooperation through Social Importance

Pedro Sequeira, Samuel Mascarenhas, Francisco S. Melo, Ana Paiva

W-58: Quantifier Learning: An Agent-based Coordination Model Dariusz Kalocinski, Nina Gierasimczuk, Marcin Mostowski



W-59: Randomized Coordination Search for Scalable Multiagent Planning

N. Kemal Ure, Jonathan P. How, John Vian

W-60: A Large-Scale Study of Agents Learning from Human Reward Guangliang Li, Hayley Hung, Shimon Whiteson

W-61: Evolution of Cooperation under Entrenchment Effects *Jayati Deshmukh, Srinath Srinivasa*

W-62: Filling Knowledge Gaps in Human-Robot Interaction Using Rewritten Knowledge of Common Verbs

Dongcai Lu, Jianmin Ji, Xiaoping Chen, Jiangchuan Liu

W-63: The RoboCup 2014 SPL Drop-in Player Competition: Encouraging Teamwork without Pre-coordination Katie Genter, Tim Laue, Peter Stone

W-64: A Heating Agent using a Personalised Thermal Comfort Model to Save Energy

Frederik Auffenberg, Sebastian Stein, Alex Rogers

W-65: Cognitive Robots Learning Failure Contexts Through Experimentation

Sertac Karapinar, Sanem Sariel

W-66: Towards Sketch Recognition by Mirroring

Mor Vered, Gal A. Kaminka

$W\mathchar`-67$: Managing Multi Robotic Agents to Avoid Congestion and Stampedes

Garima Ahuja, Kamalakar Karlapalem

Wednesday 6 May — Morning

11.00 - 12.30Game Theory I - B1Room: Üsküdar 2Chair: Makoto Yokoo

Dynamic Influence Maximization Under Increasing Returns to Scale

Haifeng Zhang, Ariel D. Procaccia, Yevgeniy Vorobeychik

Decision-theoretic Clustering of Strategies

Nolan Bard, Deon Nicholas, Csaba Szepesvári, Michael Bowling



Online Monte Carlo Counterfactual Regret Minimization for Search in Imperfect Information Games

Lisý Viliam, Marc Lanctot, Michael Bowling

Endgame Solving in Large Imperfect-Information Games

Sam Ganzfried, Tuomas Sandholm

Discretization of Continuous Action Spaces in Extensive-Form Games *Christian Kroer, Tuomas Sandholm*

Welfare Effects of Market Making in Continuous Double Auctions Elaine Wah, Michael P. Wellman

11.00 – 12.30 Social Choice I – B2 *Room: Beylerbeyi 2* Chair: Joerg Rothe

Large-Scale Election Campaigns: Combinatorial Shift Bribery

Robert Bredereck, Piotr Faliszewski, Rolf Niedermeier, Nimrod Talmon

Manipulation with Bounded Single-Peaked Width: A Parameterized Study

Yongjie Yang

Kernelization Complexity of Possible Winner and Coalitional Manipulation Problems in Voting

Palash Dey, Neeldhara Misra, Y. Narahari

On the Parameterized Complexity of Minimax Approval Voting

Neeldhara Misra, Arshed Nabeel, Harman Singh

Computational Aspects of Multi-Winner Approval Voting

Haris Aziz, Serge Gaspers, Joachim Gudmundsson, Simon Mackenzie, Nicholas Mattei, Toby Walsh

Complexity of the Winner Determination Problem in Judgment Aggregation: Kemeny, Slater, Tideman, Young

Ulle Endriss, Ronald de Haan

Parameterized Complexity Results for Agenda Safety in Judgment Aggregation

Ulle Endriss, Ronald de Haan, Stefan Szeider



11.00 - 12.30 Learning I – B3 Room: Üsküdar 1 Chair: Sandip Sen

Adaptive Budgeted Bandit Algorithms for Trust Development in a Supply-Chain

Sandip Sen, Anton Ridgway, Michael Ripley

Improving the Performance of Mobile Phone Crowdsourcing Applications

Erfan Davami, Gita Sukthankar

Selecting Robust Strategies in RTS Games via Concurrent Plan Augmentation

Abdelrahman Elogeel, Andrey Kolobov, Matthew Alden, Ankur Teredesai

CFQI: Fitted Q-Iteration with Complex Returns

Robert W Wright, Xingye Qiao, Steven Loscalzo, Lei Yu

Counterfactual Exploration for Improving Multiagent Learning

Mitchell K. Colby, Sepideh Kharaghani, Chris HolmesParker, Kagan Tumer

Policy Transfer using Reward Shaping

Tim Brys, Anna Harutyunyan, Matthew E. Taylor, Ann Nowé

11.00 - 12.30 Logic I - B4

Room: Beylerbeyi 1 Chair: Natasha Alechina

Verifying Multi-Agent Systems by Model Checking Three-valued Abstractions

Alessio Lomuscio, Jakub Michaliszyn

Parameterised Verification of Autonomous Mobile-Agents in Static but Unknown Environments Sasha Rubin

Decentralized Bisimulation for Multiagent Systems

Lei Song, Yuan Feng, Lijun Zhang

Budget-Constrained Knowledge in Multiagent Systems Pavel Naumov, Jia Tao

Module Checking of Strategic Ability Wojciech Jamroga, Aniello Murano



On the Formal Verification of Diffusion Phenomena in Open Dynamic Agent Networks

Francesco Belardinelli, Davide Grossi

11.00 – 12.30 Bio-inspired Approaches – B5

Room: Maçka Chair: Gal Kaminka

Determining Placements of Influencing Agents in a Flock

Katie Genter, Shun Zhang, Peter Stone

Particle Field Optimization: A New Paradigm for Swarm Intelligence *Nathan Bell, John B. Oommen*

Bio-inspired Practicalities: Collective Behaviour using Passive Neighbourhood Sensing

Mansoor Shaukat, Mandar Chitre

Firefly-Inspired Synchronization in Swarms of Mobile Agents *Fernando Perez-Diaz, Ruediger Zillmer, Roderich Gro§*

Swarm Robot Foraging with Wireless Sensor Motes Katherine Russell, Michael Schader, Kevin Andrea, Sean Luke

Cooperative Coevolution of Partially Heterogeneous Multiagent Systems

Jorge Gomes, Pedro Mariano, Anders Lyhne Christensen

Wednesday 6 May – Lunch Break 12.30 – 13.30

Wednesday 6 May – Posters

13.30 – 14.30 Poster Session 1 *Room: Foyer*



Wednesday 6 May — Afternoon

14.30 - 16.00Game Theory II - C1Room: Üsküdar 2Chair: Maria Polukarov

The Power of Verification for Greedy Mechanism Design *Dimitris Fotakis, Piotr Krysta, Carmine Ventre*

Difficitis Foldkis, Pioli Krysla, Carmine ventre

Computational Bundling for Auctions

Christian Kroer, Tuomas Sandholm

Mechanism Design for Daily Deals

Binyi Chen, Tao Qin, Tie-Yan Liu

Selling Tomorrow's Bargains Today

Melika Abolhassani, Hossein Esfandiari, MohammadTaghi Hajiaghayi, Hamid Mahini, David Malec, Aravind Srinivasan

Social Decision with Minimal Efficiency Loss: An Automated Mechanism Design Approach

Mingyu Guo, Hong Shen, Taiki Todo, Yuko Sakurai, Makoto Yokoo

Complexity of Mechanism Design with Signaling Costs

Andrew Kephart, Vincent Conitzer

14.30 – 16.00 Cooperation – C2

Room: Beylerbeyi 2 Chair: Ed Durfee

To Ask, Sense, or Share: Ad Hoc Information Gathering *Adam Eck, Leen-Kiat Soh*

A Mechanism for Smoothly Handling Human Interrupts in Team Oriented Plans

Alessandro Farinelli, Nicolò Marchi, Masoume M. Raeissi, Nathan Brooks, Paul Scerri

Bounty Hunters and Multiagent Task Allocation

Drew Wicke, David Freelan, Sean Luke

How to Form a Task-Oriented Robust Team

Tenda Okimoto, Nicolas Schwind, Maxime Clement, Tony Ribeiro, Katsumi Inoue, Pierre Marquis



Dynamic Theoretical Analysis of the Distributed Stochastic and Distributed Breakout Algorithms

Anton Ridgway, Roger Mailler

Efficient Inter-Team Task Allocation in RoboCup Rescue

Marc Pujol-Gonzalez, Jesus Cerquides, Alessandro Farinelli, Pedro Meseguer, Juan Antonio Rodriguez-Aguilar

14.30 – 16.00 Agent Societies – C3

Room: Üsküdar 1 Chair: Viviana Mascardi

A Semantic Framework for Socially Adaptive Agents

M. Birna van Riemsdijk, Louise Dennis, Michael Fisher, Koen V. Hindriks

Synthesising Liberal Normative Systems

Javier Morales, Maite López-Sánchez, Juan A. Rodríguez-Aguilar, Michael Wooldridge, Wamberto Vasconcelos

Practical Run-Time Norm Enforcement with Bounded Lookahead

Natasha Alechina, Nils Bulling, Mehdi Dastani, Brian Logan

Generalized Commitment Alignment

Amit K. Chopra, Munindar P. Singh

Monitoring Hierarchical Agent-based Simulation Traces

Benjamin Herd, Simon Miles, Peter McBurney, Michael Luck

A Framework for Institutions Governing Institutions

Thomas Christopher King, Tingting Li, Marina De Vos, Virginia Dignum, Catholijn M Jonker, Julian Padget, M. Birna van Riemsdijk

14.30 – 16.00 Applications I – C4 Room: Beylerbeyi 1 Chair: Gita Sukthankar

DIRECT: A Scalable Approach for Route Guidance in Selfish Orienteering Problems

Pradeep Varakantham, Hala Mostafa, Na Fu, Hoong Chuin Lau

Coordinating Measurements for Air Pollution Monitoring in Participatory Sensing Settings

Alexandros Zenonos, Sebastian Stein, Nicholas R. Jennings



Factored MDPs for Optimal Prosumer Decision-Making *Angelos Angelidakis, Georgios Chalkiadakis*

Data-Driven Agent-Based Modeling, with Application to Rooftop Solar Adoption

Haifeng Zhang, Yevgeniy Vorobeychik, Joshua Letchford, Kiran Lakkaraju

Optimizing Efficiency of Taxi Systems: Scaling-up and Handling Arbitrary Constraints

Jiarui Gan, Bo An, Chunyan Miao

HAC-ER: A Disaster Response System based on Human-Agent Collectives

Sarvapali D Ramchurn, Trung Dong Huynh, Edwin Simpson, Yuki Ikuno, Wenchao Jiang, Joel E. Fischer, Steven Reece, Jack Flann, Feng Wu, Luc Moreau, Stephen J. Roberts, Tom Rodden, Nicholas R Jennings

14.30 – 16.00 Virtual Agents and Humans I – C5

Room: Maçka Chair: Rui Prada

Adaptive Advice in Automobile Climate Control Systems

Ariel Rosenfeld, Amos Azaria, Sarit Kraus, Claudia V. Goldman, Omer Tsimhoni

Are Aggressive Agents as Scary as Aggressive Humans?

Romy Blankendaal, Tibor Bosse, Charlotte Gerritsen, Tessa de Jong, Jeroen de Man

The Fallacy of Endogenous Discounting of Trust Recommendations

Tim Muller, Yang Liu, Jie Zhang

Composing Social Interactions via Social Games

Daniel G. Shapiro, Karen Tanenbaum, Josh McCoy, Larry LeBron, Craig Reynolds, Andrew Stern, Michael Mateas, Bill Ferguson, David Diller, Kerry Moffitt, Will Coon, Bruce Roberts

Human Behavior Models for Virtual Agents in Repeated Decision Making under Uncertainty

Ming Yin, Yu-An Sun

DJ-MC: A Reinforcement-Learning Agent for Music Playlist Recommendation

Elad Liebman, Maytal Saar-Tsechansky, Peter Stone



Wednesday 6 May — Coffee and Demonstrations

16.00 – 16.30 Demonstrations 1 Rooms: Foyer, Çamlıca

Community Evacuation Planning for Bushfires Using Agent-Based Simulation

Dhirendra Singh and Lin Padgham

Agent-Based Adaptive Mobile Computing in Games

Damian Burke and Axel Heßler

Enabling Intelligence Analysis through Agent-Support: the CISpaces Toolkit

Alice Toniolo, Hengfei Li, Robin Wentao Ouyang, Timothy Dropps, Nir Oren, Timothy Norman, Mani Srivastava, John A. Allen and Paul Sullivan

Pnyx: A Powerful and User-friendly Tool for Preference Aggregation

Felix Brandt, Guillaume Chabin and Christian Geist

Aerial Robotic Simulations for Evaluation of Multi-Agent Planning in GaTAC

Kenneth Bogert, Sina Solaimanpour and Prashant Doshi

An Empathic Robotic Tutor in a Map Application

Amol Deshmukh, Aidan Jones, Srinivasan Janarthanam, Helen Hastie, Tiago Ribeiro, Ruth Aylett, Ana Paiva, Ginevra Castellano, Mary Ellen Foster, Lee Corrigan, Fotios Papadopoulos, Eugenio Di Tullio and Pedro Sequeira

How to Use OpenEASE: An Online Knowledge Processing System for Robots and Robotics Researchers

Georg Bartels, Michael Beetz, Daniel Beßler, Moritz Tenorth and Jan Winkler

Extending NormLab to spur research on norm synthesis

Javier Morales, Iosu Mendizabal, David Sánchez Pinsach, Juan Antonio Rodriguez Aguilar, Maite Lopez-Sanchez, Michael Wooldridge and Wamberto Vasconcelos

Multi-Agent Target Tracking using Particle Filters enhanced with Context Data

Rik Claessens, Alta de Waal, Pieter de Villiers, Ate Penders, Gregor Pavlin and Karl Tuyls

Multi-stage Smart Grid Optimisation with a Multiagent System

Christopher-Eyk Hrabia, Francisco Denis Pozo Pardo, Tobias Küster and Sahin Albayrak



PViz: Visualising P2P Multi-Agent Simulations

Dimitris Giouroukis, Nikos Platis and Christos Tryfonopoulos

An Affective Agent for Predicting Composite Emotions

Jun Lin, Han Yu, Chunyan Miao and Zhiqi Shen

emigo: A Large-Scale Agent-Based Social Platform for the Web Travis Steel, Dane Kuiper and Rym Z. Wenkstern

Interfacing Agents with an Industrial Assembly System for "Plug and Produce"

Nikolas Antzoulatos, Elkin Castro, Lavindra de Silva and Svetan Ratchev

A Demonstration of a Prototype for AUV Post-mission Debrief Generation from Metadata

Zhuoran Wang and Helen Hastie

Wednesday 6 May — Afternoon

16.30 - 17.50Discussion Panel — D
Theory and Practice at AAMAS: Provoking a BalanceRoom: Üsküdar 2Chair: Milind Tambe

As the AAMAS conference has matured, we seem to have shifted from initial experiments in building individual agents or multiagent systems to rigorous theoretical foundations based on increasingly sophisticated computational models; an important outcome for our field. Indeed, we now seem to have an abundance of an exciting variety of results for these computational models; but without practical validation of these models in real world applications, it may appear unclear what these results are really saying. No doubt we have had some successes in practice, but is it fair to say that we as a field are doing enough of this validation? And what do we need for this validation, e.g., do we as a field need to develop a newer science around AAMAS algorithms in the field? And what should we do to encourage such validation in real applications? We do not want this panel to simply end with a conclusion that theory and practice are both important; of course they both are. We want to dig a little deeper here trying to understand the "how" and "why" of research that is more experimental and application-oriented.



14th INTERNATIONAL CONFERENCE ON AUTONOMOUS AGENTS & MULTIAGENT SYSTEMS **2015** 4-8 May 2015 • ISTANBUL CONGRESS CENTER

Thursday 7 May 2015

Thursday 7 May — Morning

<u>Thursday 7 May — Keynote — F</u> 09.00 – 10.00

Learning Submodular Functions with Applications to Multi-Agent Systems Nina Balcan Room: Üsküdar 2 Chair: Edith Elkind

Thursday 7 May — Coffee and Posters

Indicated poster and demonstrations slots are suggestions only, as there will be both posters and demos available in all breaks. Posters will also be presented during the poster sessions by authors of full length papers who have chosen to do so.

10.00 – 11.00 Poster Session 2 *Room: Foyer*

T-01: Beyond Plurality: Truth-Bias in Binary Scoring Rules

Svetlana Obraztsova, Omer Lev, Evangelos Markakis, Zinovi Rabinovich, Jeffrey S Rosenschein

T-02: Controlling Elections by Replacing Candidates or Votes

Andrea Loreggia, Nina Narodytska, Francesca Rossi, K. Brent Venable, Toby Walsh

T-03: Voting with Social Influence: Using Arguments to Uncover Ground Truth

Alan Tsang, John A. Doucette, Hadi Hosseini

T-04: Probabilistic Copeland Tournaments

Sam Saarinen, Judy Goldsmith, Craig Tovey

T-05: Competitive Influence in Social Networks: Convergence, Submodularity, and Competition Effects

Aris Anagnostopoulos, Diodato Ferraioli, Stefano Leonardi

T-06: Parametric Mechanism Design via Quantifier Elimination

Atsushi Iwasaki, Etsushi Fujita, Taiki Todo, Hidenao Iwane, Hirokazu Anai, Mingyu Guo, Makoto Yokoo



T-07: Paving the way for Large-Scale Combinatorial Auctions

Francisco Cruz-Mencia, Jesus Cerquides, Antonio Espinosa, Juan Carlos Moure, Juan Antonio Rodriguez-Aguilar

T-08: Computing Quantal Response Equilibrium for Sponsored Search Auctions

Jiang Rong, Tao Qin, Bo An

T-09: Strategy Effectiveness of Game-Theoretical Solution Concepts in Extensive-Form General-Sum Games

Jirí Cermák, Branislav Bošanský, Nicola Gatti

T-10: An Optimal Bidimensional Multi-Armed Bandit Auction for Multiunit Procurement

Satyanath Bhat, Shweta Jain, Sujit Gujar, Yadati Narahari

T-11: Competitive Pricing for Cloud Computing in an Evolutionary Market

Bolei Xu, Tao Qin, Guoping Qiu, Tie-Yan Liu

T-12: Playing Congestion Games with Bandit Feedbacks *Po-An Chen, Chi-Jen Lu*

T-13: Mechanism Design for Resource Allocation with Applications to Ccentralized Multi-commodity Routing

Qipeng Liu, Yicheng Liu, Pingzhong Tang

T-14: Computing Pareto Optimal Agreements in Multi-issue Negotiation for Service Composition

Claudia Di Napoli, Dario Di Nocera, Silvia Rossi

T-15: Improving Fairness in Nonwasteful Matching with Hierarchical Regional Minimum Quotas

Masahiro Goto, Ryoji Kurata, Naoto Hamada, Atsushi Iwasaki, Makoto Yokoo

T-16: New Winning Strategies for the Iterated Prisoner's Dilemma

Philippe Mathieu, Jean-Paul Delahaye

T-17: Bidding in Non-Stationary Energy Markets

Pablo Hernandez-Leal, Matthew E. Taylor, Enrique Munoz de Cote, L. Enrique Sucar

T-18: Multi-Agent Task Assignment for Mobile Crowdsourcing under Trajectory Uncertainties

Cen Chen, Shih-Fen Cheng, Archan Misra, Hoong Chuin Lau



T-19: Crowdfunding Investment for Renewable Energy

Ronghuo Zheng, Ying Xu, Nilanjan Chakraborty, Katia Sycara

T-20: When Opinion Request Meets Majority Search: Avoiding Fraud in On-line Review Systems

Roberto Centeno, Ramón Hermoso

T-21: Trusted Mediator Agents to Better Manage Complex and Competitive Supply Chains

Moath Jarrah, Jie Zhang

T-22: A Computational Model of Trust Based on Message Content and Source

Célia da Costa Pereira, Andrea G. B. Tettamanzi, Serena Villata

T-23: MAP: A Computational Model for Adaptive Persuasion *Yilin Kang, Ah-Hwee Tan*

T-24: "I like this painting too": When an ECA shares appreciations to engage users

Sabrina Campano, Chloé Clavel, Catherine Pelachaud

T-25: Modelling of Personality in Agents: From Psychology to Logical Formalisation and Implementation

Sebastian Ahrndt, Johannes Fähndrich, Marco Lützenberger, Sahin Albayrak

T-26: Influencing the Learning Experience Through Affective Agent Feedback in a Real-World Treasure Hunt

Mary Ellen Foster, Amol Deshmukh, Srinivasan Janarthanam, Mei Yii Lim, Helen Hastie, Ruth Aylett

T-27: The Impact of Virtual Agent Personality on a Shared Mental Model with Humans during Collaboration

Nader Hanna, Deborah Richards

T-28: The Evolutionary Perks of Being Irrational

Fernando P. Santos, Francisco C. Santos, Ana Paiva

T-29: Towards Probabilistic Decision Making on Human Activities modeled with Business Process Diagrams

Hector G. Ceballos, Victor Flores-Solorio, Juan P. Garcia-Vazquez

T-30: Accounting for Circumstances in Reputation Assessment Simon Miles, Nathan Griffiths



T-31: The Cost of Interference in Evolving Multiagent Systems

The Anh Han, Long Tran-Thanh, Nicholas R. Jennings

T-32: Modeling Tipping Point Theory using Normative Multi-agent Systems

Rahmatollah Beheshti, Gita Sukthankar

T-33: A Bayesian Approach to Norm Identification

Stephen Cranefield, Felipe Meneguzzi, Nir Oren, Bastin Tony Roy Savarimuthu

T-34: A Multidimensional Environment Implementation for Enhancing Agent Interaction

Stéohane Galland, Flavien Balba, Nicolas Gaud, Sebastian Rodriguez, Gauthier Picard, Olivier Boissier

T-35: Programming with Commitments and Goals in JaCaMo+ Matteo Baldoni, Cristina Baroglio, Federico Capuzzimati, Roberto Micalizio

T-36: Estimating the Progress of Maintenance Goals

John Thangarajah, James Harland, Neil Yorke-Smith

T-37: An Overview of a Mapping from Processes to Agents Tobias Küster, Marco Lützenberger

T-38: Global Approximations for Principal Agent Theory

Federico Cerutti, Nir Oren, Christopher Burnett

T-39: Synchronous Games in the Situation Calculus

Giuseppe De Giacomo, Yves Lesperance, Adrian R. Pearce

T-40: Private Revision in a Multi-Agent Setting

Thomas Caridroit, Sébastien Konieczny, Tiago de Lima, Pierre Marquis

T-41: Elements of Epistemic Crypto Logic

Jan van Eijck, Malvin Gattinger

T-42: Verifying Normative System Specification containing Collective Imperatives and Deadlines

Luca Gasparini, Timothy J. Norman, Martin J. Kollingbaum, Liang Chen, John-Jules Ch. Meyer

T-43: Towards Consistency-Based Reliability Assessment

Laurence Cholvy, Laurent Perrussel, William Raynaut, Jean-Marc Thévenin



T-44: A Game for Studying Maintenance Alerts' Effectiveness

Avraham Shvartzon, Amos Azaria, Sarit Kraus, Claudia V. Goldman, Joachim Meyer, Omer Tsimhoni

T-45: Survival of the Chartist: An Evolutionary Agent-Based Analysis of Stock Market Trading

Daan Bloembergen, Daniel Hennes, Simon Parsons, Karl Tuyls

T-46: An Agent-based Simulation System for Dynamic Project Scheduling and Online Disruption Resolving

Hui Xi, Meng Sha, Chi Keong Goh, Partha Sarathi Dutta, Jie Zhang

T-47: A Gillespie-based Computational Model for Integrating Eventdriven and Multi-Agent Based Simulation

Sara Montagna, Andrea Omicini, Danilo Pianini

T-48: Exploiting Objects as Artifacts in Multi-Agent Based Social Simulations

Felicitas Mokom, Ziad Kobti

T-49: Approximating Difference Evaluations with Local Information Mitchell K. Colby, William Curran, Kagan Tumer

T-50: A Replicator Dynamics Analysis of Difference Evaluation Functions

Mitchell K. Colby, Kagan Tumer

T-51: Influence-Optimistic Local Values for Multiagent Planning Frans A. Oliehoek, Matthijs T. J. Spaan, Stefan J. Witwicki

T-52: Reinforcement Learning for Nash Equilibrium Generation David Cittern, Abbas Edalat

T-53: Behaviour Analysis of Mixed Game-Theoretic Learning Algorithms

Michalis Smyrnakis, Hongyang Qu, Sandor Veres

T-54: Using KL Divergence for Credibility Assessment Thibaut Vallée, Grégory Bonnet

T-55: Multi-Variable Agents Decomposition for DCOPs to Exploit Multi-Level Parallelism

Ferdinando Fioretto, William Yeoh, Enrico Pontelli



T-56: Large Neighborhood Search with Quality Guarantees for Distributed Constraint Optimization Problems

Ferdinando Fioretto, Federico Campeotto, Agostino Dovier, Enrico Pontelli, William Yeoh

T-57: Improving Value Function Approximation in Factored POMDPs by Exploiting Model Structure

Tiago S. Veiga, Matthijs T. J. Spaan, Pedro U. Lima

T-58: Multi-Robot Inverse Reinforcement Learning Under Occlusion with State Transition Estimation

Kenneth Bogert, Prashant Doshi

T-59: A Novel Abstraction Framework for Online Planning Ankit Anand, Aditya Grover, Mausam, Parag Singla

T-60: Considering Agent and Task Openness in Ad Hoc Team Formation Bin Chen, Xi Chen, Anish Timsina, Leen-Kiat Soh

T-61: Towards Completely Decentralized Mustering for StarCraft Zachary Suffern, Craig Tovey, Sven Koenig

T-62: PrivHab: a Multiagent Secure Georouting Protocol for Podcast Distribution on Disconnected Areas

Adrianán Sánchez-Carmona, Sergi Robles, Carlos Borrego

T-63: On Structure-Based Inconsistency Measures and Their Computations via Closed Set Packing

Said Jabbour, Yue Ma, Badran Raddaoui, Lakhdar Sais, Yakoub Salhi

T-64: Social Insect-Inspired Multi-Robot Coverage Bastian Broecker, Ipek Caliskanelli, Karl Tuyls, Elizabeth Sklar, Daniel Hennes

T-65: Some Performance Bounds of Strategies for Graph Exploration *Alessandro Riva, Alberto Quattrini Li, Francesco Amigoni*

T-66: On Task Recognition and Generalization in Long-Term Robot Teaching

Guglielmo Gemignani, Steven D Klee, Manuela Veloso, Daniele Nardi

T-67: Generalized Plan Design For Autonomous Mobile Manipulation in Open Environments

Jan Öliver Winkler, Michael Beetz



Thursday 7 May — Morning

11.00 – 12.30 Game Theory III – G1 Room: Üsküdar 2 Chair: Kate Larson

Approximately Strategy-proof Mechanisms for (Constrained) Facility Location

Xin Sui, Craig Boutilier

Facility Location Games with Dual Preference

Shaokun Zou, Minming Li

The Power of Swap Deals in Distributed Resource Allocation

Anastasia Damamme, Aurélie Beynier, Yann Chevaleyre, Nicolas Maudet

Strategic Free Information Disclosure for Search-Based Information Platforms

Shani Alkoby, David Sarne, Sanmay Das

Information Disclosure as a Means to Security

Zinovi Rabinovich, Albert Xin Jiang, Manish Jain, Haifeng Xu

Electric Boolean Games

Paul Harrenstein, Paolo Turrini, Michael Wooldridge

11.00 – 12.30 Social Choice II – G2

Room: Beylerbeyi 2 Chair: Ulle Endriss

A Study of Human Behavior in Online Voting

Maor Tal, Reshef Meir, Ya'akov (Kobi) Gal

Aggregating Partial Rankings with Applications to Peer Grading in Massive Online Open Courses

Ioannis Caragiannis, George A. Krimpas, Alexandros A. Voudouris

Computing Manipulations of Ranking Systems

Ethan Gertler, Erika Mackin, Malik Magdon-Ismail, Lirong Xia, Yuan Yi

Every Team Deserves a Second Chance: Identifying when Things Go Wrong

Vaishnavh Nagarajan, Leandro Soriano Marcolino, Milind Tambe



Adapting the Social Network to Affect Elections

Sigal Sina, Noam Hazon, Avinatan Hassidim, Sarit Kraus

Multiple Referenda and Multiwinner Elections Using Hamming Distances: Complexity and Manipulability

Georgios Amanatidis, Nathanaël Barrot, Jérôme Lang, Evangelos Markakis, Bernard Ries

11.00 – 12.30 Learning II – G3

Room: Üsküdar 1 Chair: Karl Tuyls

Learning Inter-Task Transferability in the Absence of Target Task Samples

Jivko Sinapov, Sanmit Narvekar, Matteo Leonetti, Peter Stone

R-HybrID: Evolution of Agent Controllers with a Hybrisation of Indirect and Direct Encodings

Fernando Silva, Luis Correia, Anders Lyhne Christensen

Learning By Observation Using Qualitative Spatial Relations Jay Young, Nick Hawes

Learning in Multi-agent Systems with Sparse Interactions by Knowledge Transfer and Game Abstraction

Yujing Hu, Yang Gao, Bo An

Knowledge Revision for Reinforcement Learning with Abstract MDPs *Kyriakos Efthymiadis, Daniel Kudenko*

Monte Carlo Hierarchical Model Learning

Jacob Menashe, Peter Stone

11.00 – 12.30 Applications II – G4 *Room: Beylerbeyi 1* Chair: Michael Winikoff

Supporting Reasoning with Different Types of Evidence in Intelligence Analysis

Alice Toniolo, Timothy J. Norman, Anthony Etuk, Federico Cerutti, Robin Wentao Ouyang, Mani Srivastava, Nir Oren, Timothy Dropps, John A. Allen, Paul Sullivan

Using Information Theory to Improve the Robustness of Trust Systems Dongxia Wang, Tim Muller, Athirai A. Irissappane, Jie Zhang, Yang Liu



Learning Behavior Patterns from Video: A Data-driven Framework for Agent-based Crowd Modeling

Jinghui Zhong, Wentong Cai, Linbo Luo, Haiyan Yin

Signaled Queueing

Laura Brink, Robert Shorten, Jia Yuan Yu

Modeling the Management of Water Resources Systems Using Multi-Objective DCOPs

Francesco Amigoni, Andrea Castelletti, Matteo Giuliani

A Multi-Agent Platform for Automating the Collection of Patient-Provided Clinical Feedback

Zina M. Ibrahim, Lorena Fernandez de la Cruz, Argyris Stringaris, Robert Goodman, Michael Luck, Richard J.B. Dobson

11.00 - 12.30 Robotics I - G5

Room: Maçka Chair: Paul Scerri

Real-time Opinion Aggregation Methods for Crowd Robotics

Elliot Salisbury, Sebastian Stein, Sarvapali Ramchurn

Teaching Robots Parametrized Executable Plans Through Spoken Interaction

Guglielmo Gemignani, Emanuele Bastianelli, Daniele Nardi

Frontier-Based RTDP: A New Approach to Solving the Robotic Adversarial Coverage Problem

Roi Yehoshua, Noa Agmon, Gal A Kaminka

Pervasive 'Calm' Perception for Autonomous Robotic Agents

Thiemo Wiedemeyer, Ferenc Bálint-Benczédi, Michael Beetz

Effective Approximations for Multi-Robot Coordination in Spatially Distributed Tasks

Daniel Claes, Philipp Robbel, Frans A. Oliehoek, Karl Tuyls, Daniel Hennes, Wiebe van der Hoek

Adversarial Modeling in the Robotic Coverage Problem

Roi Yehoshua, Noa Agmon



<u>Thursday 7 May – Lunch Break</u> 12.30 – 13.30

Thursday 7 May – Posters

13.30 – 14.30 Poster Session 2

Room: Foyer

Thursday 7 May — Afternoon

14.30 – 16.00 Game Theory IV – H1 Room: Üsküdar 2 Chair: Sanmay Das

Waste Makes Haste: Bounded Time Protocols for Envy-Free Cake Cutting with Free Disposal

Erel Segal-Halevi, Avinatan Hassidim, Yonatan Aumann

Fairness and False-Name Manipulations in Randomized Cake Cutting Shunsuke Tsuruta, Masaaki Oka, Taiki Todo, Yuko Sakurai, Makoto Yokoo

Bitcoin Mining Pools: A Cooperative Game Theoretic Analysis Yoad Lewenberg, Yoram Bachrach, Yonatan Sompolinsky, Aviv Zohar, Jeffrey S Rosenschein

On Sex, Evolution, and the Multiplicative Weights Update Algorithm *Reshef Meir, David Parkes*

On the Susceptibility of the Deferred Acceptance Algorithm *Haris Aziz, Hans Georg Seedig, Jana Karina von Wedel*

Hierarchical Abstraction, Distributed Equilibrium Computation, and Post-Processing, with Application to a Champion No-Limit Texas Hold'em Agent

Noam Brown, Sam Ganzfried, Tuomas Sandholm

14.30 – 16.00 Logic II – H2 Room: Beylerbeyi 2 Chair: Michael Wooldridge

A Dialogue Game for Recommendation with Adaptive Preference Models

Christophe Labreuche, Nicolas Maudet, Wassila Ouerdane, Simon Parsons



Reasoning with PCP-nets in a Multi-Agent Context

Cristina Cornelio, Umberto Grandi, Judy Goldsmith, Nicholas Mattei, Francesca Rossi, K. Brent Venable

A Logic for Collective Choice

Guifei Jiang, Dongmo Zhang, Laurent Perrussel, Heng Zhang

Propositional Opinion Diffusion Umberto Grandi, Emiliano Lorini, Laurent Perrussel

Belief Merging versus Judgment Aggregation Patricia Everaere, Sébastien Konieczny, Pierre Marguis

A Syntactic Proof of Arrow's Theorem in a Modal Logic of Social Choice **Functions**

Giovanni Ciná, Ulle Endriss

14.30 - 16.00 Engineering Agent-Based Systems – H3 Room: Üsküdar 1 Chair: Brian Logan

Global Protocols as First Class Entities for Self-Adaptive Agents Davide Ancona, Daniela Briola, Angelo Ferrando, Viviana Mascardi

A Self-Organizing Virtual Environment for Agent-Based Simulations Mohammad Al-Zinati, Rym Wenkstern

An Approach to Quantify Workload in a System of Agents

Richard Stocker, Neha Rungta, Eric Mercer, Franco Raimondi, Jon Holbrook, Colleen Cardoza, Michael Goodrich

Agent Oriented Modelling of Tactical Decision Making

Rick Evertsz, John Thangarajah, Nitin Yadav, Thanh Ly

Metrics for Evaluating Modularity and Extensibility in HMAS Systems

Massimo Cossentino, Carmelo Lodato, Salvatore Lopes, Patrizia Ribino, Valeria Palermo

Early Detection of Design Faults Relative to Requirement Specifications in Agent-Based Models

Yoosef Abushark, John Thangarajah, Tim Miller, James Harland, Michael Winikoff



14.30 - 16.00Applications III - H4Room: Beylerbeyi 1Chair: Pradeep Varakantham

Incentive Schemes for Participatory Sensing

Goran Radanovic, Boi Faltings

Truthful Interval Cover Mechanisms for Crowdsourcing Applications

Pankaj Dayama, Balakrishnan Narayanaswamy, Dinesh Garg, Y Narahari

A Truthful Budget Feasible Multi-Armed Bandit Mechanism for Crowdsourcing Time Critical Tasks

Arpita Biswas, Shweta Jain, Debmalya Mandal, Y. Narahari

TAC AdX'14: Autonomous Agents for Realtime Ad Exchange

Bingyang Tao, Fan Wu, Guihai Chen

Predicting Bundles of Spatial Locations from Learning Revealed Preference Data

Truc Viet Le, Siyuan Liu, Hoong Chuin Lau, Ramayya Krishnan

A Multiagent Approach to Variable-Rate Electric Vehicle Charging Coordination

Konstantina Valogianni, Wolfgang Ketter, John Collins

14.30 – 16.00 Planning I – H5

Room: Maçka Chair: Felipe Meneguzzi

Optimisation and Relaxation for Multiagent Planning in the Situation Calculus

Toby O. Davies, Adrian R. Pearce, Peter J. Stuckey, Harald Søndergaard

Capability Models and Their Applications in Planning

Yu Zhang, Sarath Sreedharan, Subbarao Kambhampati

Iterative Online Planning in Multiagent Settings with Limited Model Spaces and PAC Guarantees

Yingke Chen, Prashant Doshi, Yifeng Zeng

Managing Dynamic Multi-Agent Simple Temporal Network

Guillaume Casanova, Cédric Pralet, Charles Lesire

The Dependence of Effective Planning Horizon on Model Accuracy *Nan Jiang, Alex Kulesza, Satinder Singh, Richard Lewis*



Planning for Crowdsourcing Hierarchical Tasks

Ece Kamar, Eric Horvitz

Thursday 7 May — Coffee and Demonstrations

16.00 – 16.30 Demonstrations 2

Rooms: Foyer, Çamlıca

Every Team Deserves a Second Chance: An Interactive 9x9 Go Experience

Leandro Soriano Marcolino, Vaishnavh Nagarajan and Milind Tambe

Learning, Predicting and Planning Against Crime: Demonstration based on real urban crime data

Chao Zhang, Manish Jain, Ripple Goyal, Arunesh Sinha and Milind Tambe

Shaping Mario with Human Advice

Anna Harutyunyan, Tim Brys, Peter Vrancx and Ann Nowé

SCANERGY: A Scalable and Modular System for Energy Trading Between Prosumers

Mihail Mihaylov, Sergio Jurado, Narcis Avellana, Ivan Razo-Zapata, Kristof Van Moffaert, Adrian Cañadas, Leticia Arco, Isel Grau and Ann Nowe

HAC-ER: A disaster response system based on Human-Agent Collectives

Sarvapali Ramchurn, Trung Dong Huynh, Edwin Simpson, Yuki Ikuno, Wenchao Jiang, Feng Wu, Joel Fischer, Steven Reece, Stephen Roberts, Tom Rodden, Luc Moreau and Nick Jennings

Open Game Tournaments in STARLITE

Jack Hopkins, Ozgur Kafali and Kostas Stathis

Using Agent-Based Tactics Models to Control Virtual Actors in VBS3

Rick Evertsz, John Thangarajah and Nik Ambukovski

A tool for defining agent protocols in HAPN

Nitin Yadav, Lin Padgham and Michael Winikoff

SE-Star: A Large-Scale Human Behavior Simulation for Planning, Decision-Making and Training

Laurent Navarro, Fabien Flacher and Christophe Meyer



A Knowledge-Based Approach to Robotic Perception using Unstructured Information Management

Ferenc Balint-Benczedi, Thiemo Wiedemeyer, Moritz Tenorth, Daniel Bessler and Michael Beetz

PrivHab: a Multiagent Secure Georouting Protocol for Podcast Distribution on Disconnected Areas

Adrián Sánchez-Carmona, Sergi Robles and Carlos Borrego

A Framework for Developing Multi-Agent Systems in Ambient Intelligence Scenarios

Pablo Campillo-Sanchez and Jorge Gomez-Sanz

Social Theatre: Showcasing Social Power Aware Agents

Gonçalo Pereira, Rui Prada and Pedro A. Santos

fNIRS-based BCI for Robot Control

Kirill I. Tumanov, Rainer Goebel, Rico Möckel, Bettina Sorger and Gerhard Weiss

ScienceAtHome-platform for online games with a purpose

Pinja Haikka and Jacob Sherson

Thursday 7 May — Afternoon

16.30 – 17.15 Blue Sky Ideas – 11

Room: Üsküdar 2 Chair: Jeff Rosenschein

Creating Socially Adaptive Electronic Partners

M. Birna van Riemsdijk, Catholijn M. Jonker, Victor Lesser

Cybersecurity as an Application Domain for Multiagent Systems *Munindar P Singh*

Crowdsourcing Societal Tradeoffs

Vince Conitzer, Markus Brill, Rupert Freeman

16.30 – 17.15 Hedonic Games – I2

Room: Beylerbeyi 2 Chair: Haris Aziz

Fractional Hedonic Games: Individual and Group Stability

Florian Brandl, Felix Brandt, Martin Strobel

Representing and Solving Hedonic Games with Ordinal Preferences and Thresholds

Jérôme Lang, Anja Rey, Jörg Rothe, Hilmar Schadrack, Lena Schend



On the Price of Stability of Fractional Hedonic Games

Vittorio Bilò, Angelo Fanelli, Michele Flammini, Gianpiero Monaco, Luca Moscardelli

16.30 - 17.15Planning II - I3Room: Üsküdar 1Chair: Matthijs Spaan

Incremental Policy Iteration with Guaranteed Escape from Local Optima in POMDP Planning

Marek Grzes, Pascal Poupart

Predictive State Representations with State Space Partitioning *Yunlong Liu, Yun Tang, Yifeng Zeng*

Effective Influence Abstractions for Organizational Design

Jason Sleight, Edmund H. Durfee

16.30 – 17.15 Applications IV – I4

Room: Beylerbeyi 1 Chair: Amal El Fallah Seghrouchni

Near-Optimal Decentralized Power Supply Restoration in Smart Grids *Pritee Agrawal, Akshat Kumar, Pradeep Varakantham*

Designing a Marketplace for the Trading and Distribution of Energy in the Smart Grid

Jesus Cerquides, Gauthier Picard, Juan A. Rodriguez-Aguilar

AdaHeat: A General Adaptive Intelligent Agent for Domestic Heating Control

Athanasios Aris Panagopoulos, Muddasser Alam, Alex Rogers, Nicholas Robert Jennings

16.30 – 17.15 Robotics II – 15

Room: Maçka Chair: Noa Agmon

Efficient Decision-Making in a Self-Organizing Robot Swarm: On the Speed Versus Accuracy Trade-Off

Gabriele Valentini, Heiko Hamann, Marco Dorigo

Pipelined Consensus for Global State Estimation in Multi-Agent Systems

Golnaz Habibi, Zachary Kingston, Zijian Wang, Mac Schwager, James McLurkin



Continuous Foraging and Information Gathering in a Multi-Agent Team

Somchaya Liemhetcharat, Rui Yan, Keng Peng Tee

Thursday 7 May — Afternoon

17.15 – 18.15 2014 IFAAMAS Victor Lesser Distinguished Dissertation Award Talk — J

Room: Üsküdar 2 Chair: Michael Winikoff

Arbitration, Fairness and Stability: Revenue Division in Collaborative Settings

Yair Zick

<u>Thursday 7 May — Evening</u> 19.30 – 23.30

Gala Dinner

The gala dinner will take place at Portaxe Restaurant. Reserved for participants with tickets. (Please see page 63 for details.)



Friday 8 May 2015

Friday 8 May — Morning

<u>Friday 8 May — Keynote — K</u> 09.00 – 10.00

Greta, an Interactive Expressive Embodied Conversational Agent *Catherine Pelachaud*

Room: Üsküdar 2 Chair: Milind Tambe

Friday 8 May — Coffee, Posters, and Demonstrations

10.00 – 11.00 Poster Session *Rooms: Foyer, Çamlıca*

All paper authors and demonstration presenters are welcome to present during the Friday coffee break session, subject to space availability on a first come, first served basis.

Friday 8 May — Morning

11.00 - 12.30 Game Theory V - L1 *Room: Üsküdar 2* Chair: Bo An

Robust Strategy against Unknown Risk-averse Attackers in Security Games

Yundi Qian, William Haskell, Milind Tambe

Keeping Pace with Criminals: Designing Patrol Allocation Against Adaptive Opportunistic Criminals

Chao Zhang, Arunesh Sinha, Milind Tambe

It Pays to Pay in Bi-Matrix Games – a Rational Explanation for Bribery *Anshul Gupta, Sven Schewe*

Two-Timescale Algorithms for Learning Nash Equilibria in General-Sum Stochastic Games

H.L. Prasad, Prashanth L.A., Shalabh Bhatnagar

A Game of Thrones

Debarun Kar, Fei Fang, Francesco Maria Delle Fave, Nicole Sintov, Milind Tambe



Stackelberg Games for Vaccine Design

Swetasudha Panda, Yevgeniy Vorobeychik

11.00 – 12.30 Social Choice III – L2 *Room: Beylerbeyi 2* Chair: Jerome Lang

General Tiebreaking Schemes for Computational Social Choice

Rupert Freeman, Markus Brill, Vincent Conitzer

Incentives for Participation and Abstention in Probabilistic Social Choice

Florian Brandl, Felix Brandt, Johannes Hofbauer

Sample Complexity for Winner Prediction in Elections

Palash Dey, Arnab Bhattacharyya

How Credible is the Prediction of a Party-Based Election?

Jiong Guo, Yash Raj Shrestha, Yongjie Yang

Detecting Possible Manipulators in Elections

Palash Dey, Neeldhara Misra, Y. Narahari

Manipulating the Probabilistic Serial Rule

Haris Aziz, Serge Gaspers, Simon Mackenzie, Nicholas Mattei, Nina Narodytska, Toby Walsh

11.00 – 12.30 Logic III – L3

Room: Üsküdar 1 Chair: Alessio Lomuscio

Efficient Reasoning With Consistent Proper Epistemic Knowledge Bases

Christian Muise, Tim Miller, Paolo Felli, Adrian R Pearce, Liz Sonenberg

Arbitrary Public Announcement Logic with Mental Programs

Tristan Charrier, Fran lois Schwarzentruber

Neuro-Symbolic Agents: Boltzmann Machines and Probabilistic Abstract Argumentation with Sub-Arguments

Regis Riveret, Jeremy Pitt, Dimitrios Korkinof, Moez Draief

Agreeing to Agree: Reaching Unanimity via Preference Dynamics Based on Reliable Agents

Sujata Ghosh, Fernando R. Velázquez-Quesada



Analysis Problems for Graphical Dynamical Systems: A Unified Approach Through Graph Predicates

Daniel J. Rosenkrantz, Madhav V. Marathe, Harry B. Hunt III, S. S. Ravi, Richard E. Stearns

Argumentation-based Ranking Logics

Leila Amgoud, Jonathan Ben-Naim

11.00 – 12.30 Virtual Agents and Humans II – L4

Room: Beylerbeyi 1 Chair: Catholijn Jonker

Modeling Students Self-Studies Behaviors

Pedro Mota, Francisco Melo, Luísa Coheur

Beyond Traits: Social Context Based Personality Model

Jaroslaw Kochanowicz, Ah-Hwee Tan, Daniel Thalmann

Incorporating Global and Local Knowledge in Intentional Narrative Planning

Jonathan Teutenberg, Julie Porteous

Automated Extension of Narrative Planning Domains with Antonymic Operators

Julie Porteous, Alan Lindsay, Jonathon Read, Mark Truran, Marc Cavazza

Semi-feature Level Fusion for Bimodal Affect Regression Based on Facial and Bodily Expressions

Yang Zhang, Li Zhang

An Effective Conversation Tactic for Creating Value over Repeated Negotiations

Johnathan Mell, Gale Lucas, Jonathan Gratch

11.00 – 12.30 Robotics III – L5

Room: Maçka Chair: Alessandro Farinelli

Adaptive Learning for Multi-Agent Navigation

Julio E Godoy, Ioannis Karamouzas, Stephen J Guy, Maria Gini

Detecting and Correcting Model Anomalies in Subspaces of Robot Planning Domains

Juan Pablo Mendoza, Manuela Veloso, Reid Simmons



Solving Infrastructure Monitoring Problems with Multiple Heterogeneous Unmanned Aerial Vehicles

Jakub Ondracek, Ondrej Vanek, Michal Pechoucek

Observation Modelling for Vision-Based Target Search by Unmanned Aerial Vehicles

W. T. Luke Teacy, Simon J. Julier, Renzo De Nardi, Alex Rogers, Nicholas R. Jennings

Sliding Autonomy for UAV Path-Planning: Adding New Dimensions to Autonomy Management

Lanny Lin, Michael A Goodrich

Leading the Way: An Efficient Multi-robot Guidance System

Piyush Khandelwal, Samuel Barrett, Peter Stone

Friday 8 May — Lunch and Community Meeting

12.30 – 14.30 Community Meeting *Room: Üsküdar 2*



Keynote Speakers

Wednesday 6 May 2015 09.00 - 10.00

On the Full Organism Challenge: Or, Can we Computerize an Elephant?

Prof. David Harel Weizmann Institute of Science in Israel

Room: Üsküdar 2

We show how techniques from computer science and software engineering can be applied beneficially to research in the life sciences. I will discuss the idea of comprehensive and realistic modeling of biological systems, where we try to understand and analyze an entire system in detail, utilizing in the modeling effort all that is known about it. I will address the motivation for such modeling and the philosophy underlying the techniques for carrying it out, as well as the crucial question of when such models are to be deemed valid, or complete. The examples will be from among the biological modeling efforts my group has been involved in: T cell development, lymph node behavior, organogenesis of the pancreas, rat whisking, cancer tumor formation, and various projects regarding the C. elegans nematode. The ultimate long-term "grand challenge" is to produce an interactive, dynamic, computerized model of an entire multi-cellular organism, such as the C. elegans, which is extremely complex despite its small size, but welldefined in terms of anatomy and genetics. The sweeping potential benefits of such a model will be discussed.

Biography: Prof. David Harel has been at the Weizmann Institute of Science in Israel since 1980. He was Department Head from 1989 to 1995, and was Dean of the Faculty of Mathematics and Computer Science between 1998 and 2004. He was also co-founder of I-Logix, Inc. He received his PhD from MIT in 1978, and has spent time at IBM Yorktown Heights, and sabbaticals at Carnegie-Mellon, Cornell, and the University of Edinburgh. In the past he worked mainly in theoretical computer science (logic, computability, automata, database theory), and he now works mainly on software and systems engineering and on modeling biological systems. He is the inventor of Statecharts and co-inventor of Live Sequence Charts (LSCs), and co-designed Statemate, Rhapsody, the Play-Engine and PlayGo. Among his books are "Algorithmics: The Spirit of Computing" and "Computers Ltd.:



What They Really Can't Do", and his awards include the ACM Karlstrom Outstanding Educator Award (1992), the Israel Prize (2004), the ACM Software System Award (2007), the Emet Prize (2010), and five honorary degrees. He is a Fellow of ACM, IEEE and AAAS, a member of the Academia Europaea and the Israel Academy of Sciences, and a foreign member of the US National Academy of Engineering and the American Academy of Arts and Sciences.

Thursday 7 May 2015 09.00 – 10.00

Learning Submodular Functions with Applications to Multi-Agent Systems

Dr. Maria Florina Balcan School of Computer Science, Carnegie Mellon University, USA

Room: Üsküdar 2

Machine learning can provide powerful tools for the design and analysis of multi-agent systems, as well as a novel lens on important questions in the area. In this talk I will focus on the use of machine learning for understanding submodular functions, an important class of discrete functions that model laws of diminishing returns and enjoy many important applications in multi-agent settings. For example, submodular functions are commonly used to model valuation functions for bidders in auctions, the influence of various subsets of agents in social networks, and the benefits of performing different actions in a variety of situations. Traditionally it is assumed that these functions are known to the decision maker; however, for large scale systems, in the age of big data, it is often the case they must be learned from observations.

In this talk, I will discuss a recent line of work on studying the learnability of submodular functions, and highlight its applications to the analysis of multi-agent systems. I will discuss both general algorithms for learning such functions, as well as even better guarantees that can be achieved for important classes appearing in multi-agent scenarios that exhibit additional structure. These classes include: probabilistic coverage functions that can be used to model the influence function in classic models of information diffusion in networks; functions with bounded complexity used in modeling bidder valuation functions in auctions, including XOS and gross-substitutes; and classes of functions appearing in cooperative game theory for expressing the values of various types of coalitions.



I will additionally discuss a large scale application of our algorithms for learning the influence functions in social networks, that significantly outperforms existing approaches empirically in both synthetic and real world data.

Biography: Maria Florina Balcan is an Associate Professor in the School of Computer Science at Carnegie Mellon University. Her main research interests are machine learning, computational aspects in economics and game theory, and algorithms. Her honors include the CMU SCS Distinguished Dissertation Award, an NSF CAREER Award, a Microsoft Faculty Research Fellowship, a Sloan Research Fellowship, and several paper awards at COLT. She is currently a board member of the International Machine Learning Society and was recently Program Committee chair for COLT 2014.

Friday 8 May 2015 09.00 - 10.00

Greta, an Interactive Expressive Embodied Conversational Agent

Dr. Catherine Pelachaud Director of Research CNRS, LTCI, TELECOM ParisTech, France Winner of 2015 ACM/SIGAI Autonomous Agents Award

Room: Üsküdar 2

Greta is an interactive Embodied Conversational Agent platform. It is endowed with socio-emotional and communicative behaviors. Through its behaviors, the agent can sustain a conversation as well as show various attitudes and levels of engagement.

Through the years, we have integrated all our research in the Greta platform. By applying different methodologies, based on corpus analysis, usercentered, or motion capture, we have enriched the agent's palette of multimodal behaviors. We have conducted various studies to simulate communicative behaviors, emotional behaviors, social attitudes and behavior expressivity. In particular we have proposed models to go beyond the prototypical expressions of emotions. Through its behaviors patterns, the agent can display complex emotions such as masking one expression of emotions by another ones, its relationship towards its interlocutors, specific social signals such as smile and laughter. In an interaction, the agent can be a speaker or a listener. It can exhibit backchannels, mimic on the fly its interlocutor's behaviors. To develop our models, we rely on theoretical models from social psychology literature and on data analysis.



After describing our platform, we will first review our rationale; then we will introduce our model of socio-emotional behaviors. Finally we will present experiments where we measure the impact of the agent's copying behaviors on the user's level of engagement.

Biography: Catherine Pelachaud is a Director of Research at CNRS in the laboratory LTCI, TELECOM ParisTech. She participated to the elaboration of the first embodied conversation agent system, GestureJack, with Justine Cassell, Norman Badler and Mark Steedman when being a post-doctorate at the University of Pennsylvania. She went to Università di Roma "La Sapienza" with a Marie-Curie CEE scholarship. Her research interest includes embodied conversational agent, nonverbal communication (face, gaze, and gesture), expressive behaviors and socio-emotional agents. With her research team, she has been developing an interactive virtual agent platform GRETA that can display socio-emotional and communicative behaviors. She has been involved and is still involved in several European projects related to believable embodied conversational agents, emotion and social behaviors. She is associate editors of several journals among which IEEE Transactions on Affective Computing, ACM Transactions on Interactive Intelligent Systems and Journal on Multimodal User Interfaces. She has co-edited several books on virtual agents and emotion-oriented systems. She participated to the organization of international conferences such as IVA, ACII and AAMAS, virtual agent track.



AAMAS Awards 2015

There are a number of awards associated with the AAMAS 2015 conference. The winners of these awards will be announced at the AAMAS gala dinner.

Best Paper Nominations

The following papers (in alphabetical order by author) have been nominated for Best Paper:

The Dependence of Effective Planning Horizon on Model Accuracy *Nan Jiang, Alex Kulesza, Satinder Singh, Richard Lewis*

Efficient Decision-Making in a Self-Organizing Robot Swarm: On the Speed Versus Accuracy Trade-Off

Gabriele Valentini, Heiko Hamann, Marco Dorigo

Dynamic Influence Maximization under Increasing Returns to Scale Haifeng Zhang, Ariel Procaccia, Yevgeniy Vorobeychik

Best Paper of the Innovative Applications Track

The following papers (in alphabetical order by author) have been nominated for Innovative Applications Track Best Paper:

Improving the Performance of Mobile Phone Crowdsourcing Applications

Erfan Davami, Gita Sukthankar

A Mechanism for Smoothly Handling Human Interrupts in Team Oriented Plans

Alessandro Farinelli, Nathan Brooks, Nicolò Marchi, Masoume Raeissi, Paul Scerri

HAC-ER: A Disaster Response System based on Human-Agent Collectives

Sarvapali Ramchurn, Edwin Simpson, Joel Fischer, Trung Dong Huynh, Yuki Ikuno, Steve Reece, Wenchao Jiang, Feng Wu, Jack Flann, Stephen J. Roberts, Luc Moreau, Tom Rodden, Nick Jennings



Pragnesh Jay Modi Best Student Paper

The following papers (in alphabetical order by author) have been nominated for Pragnesh Jay Modi Best Student Paper:

Factored MDPs for Optimal Prosumer Decision-Making

Angelos Angelidakis, Georgios Chalkiadakis

Particle Field Optimization: A New Paradigm for Swarm Intelligence *Bell Nathan, John Oommen*

Welfare Effects of Market Making in Continuous Double Auctions Elaine Wah, Michael Wellman

IFAAMAS Victor Lesser Distinguished Dissertation Award

This award was started for dissertations defended in 2006 and is named for Professor Victor Lesser, a long standing member of the AAMAS community who has graduated a large number of outstanding PhD students in the area. To be eligible for the 2014 award, a dissertation had to have been written as part of a PhD defended during the year 2014, and had to be nominated by the supervisor with three supporting references. Selection is based on originality, depth, impact and written quality, supported by quality publications. Previous winners of this award were Manish Jain (2013), Birgit Endrass (2012), Daniel Villatoro (2011), Bo An (2010), Andrew Gilpin (2009), Ariel Procaccia (2008), Radu Jurca (2007), and Vincent Conitzer (2006).

The 2014 IFAAMAS Victor Lesser Distinguished Dissertation Award recipient is Dr. Yair Zick, whose thesis titled "Arbitration, Fairness and Stability: Revenue Division in Collaborative Settings" was supervised by Dr. Edith Elkind. The committee also wanted to recognise two other nominees (unordered): Dr. Tim Baarslag, whose thesis titled "What to Bid and When to Stop" was supervised by Prof. Catholijn Jonker and Dr. Koen Hindriks; and Dr. Xi (Alice) Gao, whose thesis titled "Eliciting and Aggregating Truthful and Noisy Information" was supervised by Assoc. Prof. Yiling Chen.



ACM/SIGAI Autonomous Agents Award

The ACM SIGART Autonomous Agents Research Award is an annual award for excellence in research in the area of autonomous agents. The award is intended to recognize researchers in autonomous agents whose current work is an important influence on the field. The award is an official ACM award, funded by an endowment created by ACM SIGART from the proceeds of previous Autonomous Agents conferences. Candidates for the award are nominated through an open nomination process. Previous winners of the SIGART Autonomous Research Award were Michael Wellman (2014), Jeffrey S. Rosenschein (2013), Moshe Tennenholtz (2012), Joe Halpern (2011), Jonathan Gratch and Stacy Marsella (2010), Manuela Veloso (2009), Yoav Shoham (2008), Sarit Kraus (2007), Michael Wooldridge (2006), Milind Tambe (2005), Makoto Yokoo (2004), Nick Jennings (2003), Katia Sycara (2002), and Tuomas Sandholm (2001).

The selection committee for the ACM/SIGAI Autonomous Agents Research Award is pleased to announce that Dr. Catherine Pelachaud, Director of Research at CNRS at Telecom ParisTech is the recipient of the 2015 award. Dr. Pelachaud is honored for her sustained and substantial contributions to the area of intelligent virtual agents. Her seminal work in this area helped launch the area of intelligent virtual agents, and her many subsequent publications have exerted a strong influence on virtual agent research at AAMAS and the Intelligent Virtual Agents conferences. Furthermore, her research on the role that bodily communication plays in face-to-face interaction has helped set the agenda of embodied agent research. In the process, it has firmly established a research area of modeling the body, its relation to the mind and its role in social interaction. Overall, this work has filled critical gaps in agents research often ignored by the larger community.

IFAAMAS Influential Paper Award

This year's IFAAMAS Influential Paper Award winner is Prof. Michael Littman, in recognition of his distinguished contributions to the field as exemplified by the following influential paper:

Michael L. Littman. Markov games as a framework for multi-agent reinforcement learning. Proceedings of the Eleventh International Conference on Machine Learning (ICML-94), New Brunswick, NJ, pp. 157-163, 1994.



AAAI Membership

AAMAS is pleased to acknowledge its cooperation with the Association for the Advancement of Artificial Intelligence (AAAI) (www.aaai.org), which will be publicizing the conference to its membership.

Of special interest to conference attendees is an introductory membership offer from AAAI, which provides a complimentary one-year online membership to conference participants who are new to AAAI.

Please send a message to membership15@aaai.org for further details.

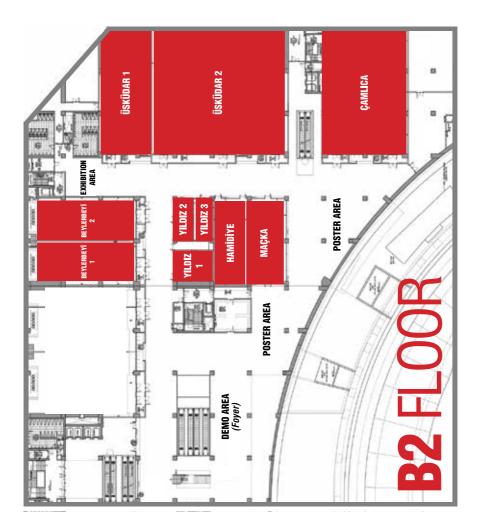


AAMAS 2015 Situation Map





AAMAS 2015 Floor Maps





R00M 85 ROOM 86 R00M 82 Ħ З R00M 87 ROOM 67 Ħ ROOM 88 R00M 70 ROOM 61 1 E ROOM 60 R00M 22 **R00M 21 ROOM 20** ENTRANCE



Reception

The welcome reception will take place at Boğaziçi University South Campus (Güney Kampüs), Albert Long Hall, on Tuesday May 5 from 19.00 to 21.30.

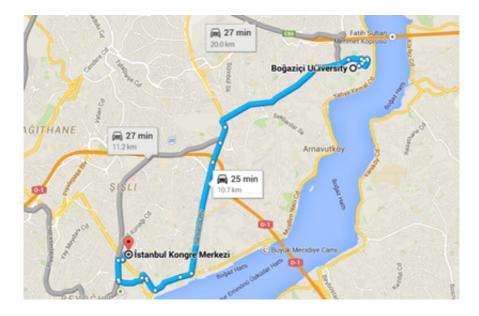
Address

Boğaziçi University 34342 Bebek/Istanbul

Access

Metro line: M2 (from Taksim) and then change to M6. Get off at Boğaziçi University stop.

Bus lines: 559 C (from Taksim), 59R (from Şişli), 43R (from Kabataş). Get off at Boğaziçi University Bus Stop.





Gala Dinner

The gala dinner will take place at Portaxe Restaurant, on Thursday 7 May from 19.30 to 23.30. The restaurant is located in the heart of the Bosporus on the European side with a magnificent view of the Asian side.

Reserved for participants with tickets.



Address

Baltalimanı Cad. No 60, Baltalimanı, Istanbul Phone: (0212) 277 8233

Access

Buses from Istanbul Congress Center will depart at 18.45.



General Information

Venue

AAMAS 2015 will be held at: Istanbul Congress Center (ICC) Taşkışla Caddesi, Harbiye 34367, Istanbul, Türkiye Tel: +90 212 373 99 00, Fax: +90 212 373 99 43, www.iccistanbul.com

Registration and Information Desk

Registration and information desk operates at the entrance of the ICC (level 0). Opening hours:

Monday 4 May: 07.00 - 19.00 Tuesday 5 May: 07.00 - 19.00 Wednesday 6 May: 07.00 - 19.00 Thursday 7 May: 08.00 - 19.00 Friday 8 May: 08.00 - 15.00

Badges

Please make sure that you wear your badge at every event you attend, including lunches and social events (reception, gala dinner).

Liability and Insurance

Registration fees do not include the insurance of participants against personal accidents, sickness and cancellations by any party, theft, loss or damage to personal possessions.

Internet / WiFi

Wireless internet is available to conference participants in all meeting rooms and foyers.

Network name: AAMAS2015 Username: Aamasistanbul Password: aamas15

Banks, Currency, Credit Cards

The local currency is the Turkish Lira (TL). Foreign currency can be exchanged at the airport as well as at private exchange offices found throughout the city (usually open from 08:30 to 20:00). In addition,



Traveller's Cheques and Eurocheques can be cashed at the local banks (open between 08:30 and 17:00). There are many banks and ATMs between Istanbul Congress Center and Taksim Square. Major debit and credit cards are accepted in most Turkish restaurants and shops.

Airport Access

Atatürk Airport is located 24 km west of the city centre (the Taksim area).

- Taxi approx. 45 minutes. Cost by taxi is approximately 60 TL (\in 20).
- Havataş Shuttle Services: Every half hour, journey time approx. 40 minutes, but it may vary according to the intensity of the traffic. Route: Departure: Taksim Aksaray Sahil Yolu Atatürk Airport. Return: Atatürk Airport Sahil Yolu Aksaray Taksim. Ticket price: 11 TL. Timetable: www.havatas.com/en/
- Private transfer can be booked through the conference secretariat.

City Transport

Istanbul has an extensive metro and bus system. Taxis are yellow and they all have meters. The opening charge is 3.20 TL and charge per km is 2.00 TL. The same flat rate is in force 24 hours a day.

Time Zone

Turkey is two hours ahead of Greenwich Mean Time (GMT) and seven ahead of Eastern Standard Time (EST). Daylight saving time is observed.

Electricity

The electric current is 220V AC with a frequency of 50 Hertz. European standard plugs with two round pins are used.

Tipping

Service charges are included in the cost of all goods and services. Although it is not mandatory, a small tip is customary for good service. As a guideline, add about 10% to the total bill. When paying by credit card, a cash tip is preferred.

Dining Out

Istanbul is a culinary delight no matter what your budget. From simple workers' eateries and sidewalk cafes to posh culinary palaces with liveried



waiters, Turkish cuisine is good and the value-for-money unbeatable. A typical Turkish dish generally consists of lamb, mutton, and veal with a variety of vegetables. Pilaf, all kinds of pastry, bulgur, haricot beans, rich olive oil, and vegetables are also common side dishes. Meatballs, shish kebab, and doner kebab are also classic dishes. Because of its coastal location, fish is also popular although it is usually cooked simply, such as grilled, or fried with olive oil and lemon juice. Istanbul is the commercial and cultural centre of Turkey, and there are restaurants of many nationalities such as Korean, Russian, Italian, and Chinese. American-style fast-food outlets are becoming more popular, but for a quick snack it is more appropriate to fill up at the plethora of tiny takeaways offering kebabs and snacks. It is easy to sample good quality regional cuisine in typical small restaurants, usually at low cost, especially in the commercial and business areas.

See page 67 for a map of restaurants close to the conference venue.

Shopping in Istanbul

Famed as the City of a Thousand Colours and Fragrances, Istanbul is a paradise for shoppers. A large variety of traditional carpets, jewels, gold, and leather goods can be purchased on the street in the tourist areas, or one can visit the city's modern shopping malls where Turkish brand goods can be found. The shops are open from 08.00 to 21.00 from Monday to Saturday. The Grand Bazaar and Spice Bazaar open their gates at 08.00 and close at 19.00. The large shopping malls open from 10.00 to 22.00 seven days a week. Shops do not close for lunch.

Daily and Post-Conference Tours

There is a lot to be seen in Istanbul and Turkey. A selection of tours will be available throughout the conference including the famous sites at the Historical Peninsula—also known as the Old City—and Bosphorus cruises. The Aegean, Anatolian and Mediterranean sections of Turkey are also packed with archaeological sites of varying ancient civilizations and can be visited in post-conference tours.

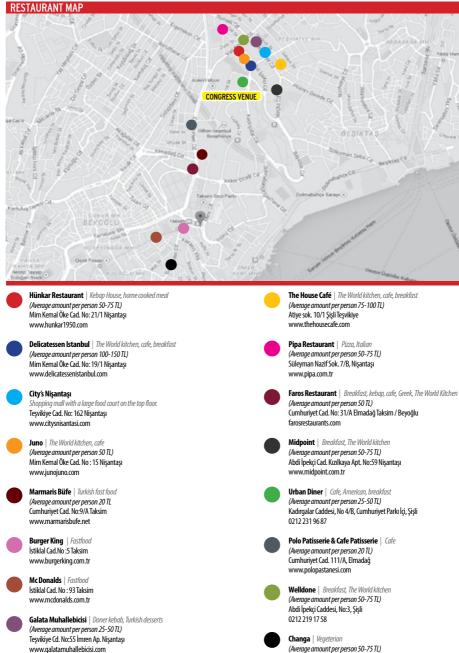
Useful Telephone Numbers

Ambulance: 112 Police: 155 Fire Brigade: 110



14th INTERNATIONAL CONFERENCE ON AUTONOMOUS AGENTS & MULTIAGENT SYSTEMS **2015**

4-8 May 2015 • ISTANBUL CONGRESS CENTER



(Average amount per person 50-75 TL) Sıraselviler Cad. No :41 Taksim www.changa-istanbul.com



Call for Participation (AAMAS'16)



9-13 May 2016, Singapore

AAMAS is the leading scientific conference for research in autonomous agents and multiagent systems. The AAMAS conference series was initiated in 2002 by merging three highly respected meetings: the International Conference on Multi-Agent Systems (ICMAS); the International Workshop on Agent Theories, Architectures, and Languages (ATAL); and the International Conference on Autonomous Agents (AA). The aim of the joint conference is to provide a single, high-profile, internationally respected archival for scientific research in the theory and practice of autonomous agents and multiagent systems.

AAMAS 2016, the fifteenth conference in the AAMAS series, seeks the submission of high-quality papers limited to 8 pages in length. Reviews will be double blind; authors must avoid including anything that can be used to identify them. Please note that submitting an abstract is required to submit a full paper. However, the abstracts will not be reviewed and full (8-page) papers must be submitted for the review process to begin. All work must be original, i.e., it must not have appeared in a conference proceedings, book, or journal and may not be under review for another archival conference. In addition to submissions in the main track, AAMAS 2016 will be soliciting papers in special tracks. The review process for the special tracks will be similar to the main track, but with programme committee members specially selected for each track. All accepted papers for the special tracks will be included in the proceedings.

General Chairs:	Catholijn Jonker (Delft University of Technology, Netherlands) Stacy Marsella (Northeastern University, USA)				
Program Chairs:	Karl Tuyls (University of Liverpool, UK) John Thangarajah (RMIT University, Australia)				

The full call for papers, along with descriptions of the special tracks and all topics of interest, and the important dates will be made available at: http://sis.smu.edu.sg/aamas2016



14th INTERNATIONAL CONFERENCE ON AUTONOMOUS AGENTS & MULTIAGENT SYSTEMS **2015**

4-8 May 2015 • ISTANBUL CONGRESS CENTER

AAMAS 2015 main conference programme

17:15	16:30	16:00	14:30	13:30	12:30	11:00	10:00	08:45 09:00	
	D Panel – Theory and Practice at AAMAS: Provoking a Balance	Demos 1	C1 Game Theory II C2 Cooperation C3 Agent Societies C4 Applications I C5 Virtual Agents I	Posters 1	Lunch break	B1 Game Theory I B2 Social Choice I B3 Learning I B4 Logic I B5 Bio-inspired Approaches	Posters 1	Opening A Keynote: Harel	Wednesday 6
J Dissertation Award Talk: Zick	 11 Blue Sky Ideas 12 Hedonic Games 13 Planning II 14 Applications IV 15 Robotics II 	Demos 2	 H1 Game Theory IV H2 Logic II H3 Eng, Agent-Based Systems H4 Applications III H5 Planning I 	Posters 2	Lunch break	G1 Game Theory III G2 Social Choice II G3 Learning II G4 Applications II G5 Robotics I	Posters 2	F Keynote: Balcan	Thursday 7
					Community meeting	L1 Game Theory V L2 Social Choice IIII L3 Logic IIII L4 Virtual Agents II L5 Robotics III	Demos and Posters	K ACM AA Award Talk: Pelachaud	Friday 8



2015

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