

Complexity of Controlling Nearly Single-Peaked Elections Revisited

Extended Abstract

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ABSTRACT

In this paper, we investigate the complexity of CONSTRUCTIVE CONTROL BY ADDING/DELETING VOTES (CCAV/CCDV) for r -approval, Condorcet, Maximin and Copeland $^\alpha$ in k -axes and k -candidate partition single-peaked elections. In general, we prove that CCAV and CCDV for most of the voting correspondences mentioned above are NP-hard even when k is a very small constant. Exceptions are CCAV and CCDV for Condorcet and CCAV for r -approval in k -axes single-peaked elections, which we show to be fixed-parameter tractable with respect to k . In addition, we give a polynomial-time algorithm for recognizing 2-axes elections, resolving an open question.

KEYWORDS

election control; parameterized complexity; nearly single-peaked

ACM Reference Format:

Yongjie Yang. 2018. Complexity of Controlling Nearly Single-Peaked Elections Revisited. In *Proc. of the 17th International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2018)*, Stockholm, Sweden, July 10–15, 2018, IFAAMAS, 3 pages.

1 PRELIMINARIES

An *election* is a tuple $\mathcal{E} = (C, \Pi_{\mathcal{V}})$, where C is a set of *candidates* and $\Pi_{\mathcal{V}}$ a multiset of *votes*, each of which is defined as a linear order over C . For a vote π and a candidate c , let $\pi(c)$ denote the position of c in π . In particular, the first-ranked candidate has position 1, the second-ranked candidate has position 2, and so forth. We use $N(c, c')$ to denote the number of votes ranking c above c' . For two candidates c and c' , we say c *beats* c' if $N(c, c') > N(c', c)$, and c *ties* c' if $N(c, c') = N(c', c)$. For $C \subseteq \mathcal{C}$ and a vote $\pi \in \Pi_{\mathcal{V}}$, π^C is π restricted to C , i.e., for $c, c' \in C$, $\pi(c) < \pi(c')$ implies $\pi^C(c) < \pi^C(c')$. Let $\Pi_{\mathcal{V}}^C = \{\pi^C \mid \pi \in \Pi_{\mathcal{V}}\}$. Hence, $(C, \Pi_{\mathcal{V}}^C)$ is the election $(C, \Pi_{\mathcal{V}})$ restricted to C .

An election $(C, \Pi_{\mathcal{V}})$ is *single-peaked* if there is a linear order \triangleleft of C , called an *axis*, such that for every vote $\pi \in \Pi_{\mathcal{V}}$ and every three candidates $a, b, c \in C$ with $a \triangleleft b \triangleleft c$ or $c \triangleleft b \triangleleft a$, $\pi(c) < \pi(b)$ implies $\pi(b) < \pi(a)$. An election $(C, \Pi_{\mathcal{V}})$ is *k -axes single-peaked* if there are k axes $\triangleleft_1, \dots, \triangleleft_k$ such that every $\pi \in \Pi_{\mathcal{V}}$ is single-peaked with respect to at least one of these axes. In addition, $(C, \Pi_{\mathcal{V}})$ is

k -candidate partition (CP) single-peaked if there is a k -partition (C_1, \dots, C_k) of C such that $(C_i, \Pi_{\mathcal{V}}^{C_i})$, $1 \leq i \leq k$, is single-peaked.

A *voting correspondence* φ is a function that maps an election $\mathcal{E} = (C, \Pi_{\mathcal{V}})$ to a non-empty subset $\varphi(\mathcal{E})$ of C . We call the elements in $\varphi(\mathcal{E})$ the *winners* of \mathcal{E} with respect to φ . In this paper, we study the following voting correspondences [6, 11, 14].

r -Approval Each vote approves exactly the top- r ranked candidates. Winners are those with the most approvals. We study only the case where r is a constant.

Borda The Borda score of a candidate $c \in C$ is defined as $\sum_{c' \in C \setminus \{c\}} N(c, c')$. Winners are the ones with the highest Borda score.

Copeland $^\alpha$ ($0 \leq \alpha \leq 1$) For a candidate c , let $B(c)$ (resp. $T(c)$) be the set of candidates beaten by c (resp. tie with c). The Copeland $^\alpha$ score of c is $|B(c)| + \alpha \cdot |T(c)|$. Copeland $^\alpha$ winners are those with the highest Copeland $^\alpha$ score.

Maximin The Maximin score of a candidate c is defined as $\min_{c' \in C \setminus \{c\}} N(c, c')$. Maximin winners are the ones with the highest Maximin score.

A candidate is the *Condorcet winner* if it beats all other candidates [25]. We slightly abuse the term Condorcet by considering it as the following voting correspondence: if the Condorcet winner exists, it is the unique winner; otherwise, all candidates win.

For a voting correspondence φ , we study the following problems.

CONSTRUCTIVE CONTROL BY ADDING VOTES (CCAV)	
Given:	An election $(C, \Pi_{\mathcal{V}})$, a distinguished candidate $p \in C$, a multiset $\Pi_{\mathcal{W}}$ of votes, and a positive integer ℓ .
Question:	Is there $\Pi_{\mathcal{W}} \subseteq \Pi_{\mathcal{V}}$ such that $ \Pi_{\mathcal{W}} \leq \ell$ and p wins $(C, \Pi_{\mathcal{V}} \cup \Pi_{\mathcal{W}})$ with respect to φ ?
CONSTRUCTIVE CONTROL BY DELETING VOTES (CCDV)	
Given:	An election $(C, \Pi_{\mathcal{V}})$, a distinguished candidate $p \in C$, and a positive integer ℓ .
Question:	Is there $\Pi_{\mathcal{V}} \subseteq \Pi_{\mathcal{V}}$ such that $ \Pi_{\mathcal{V}} \leq \ell$ and p wins the election $(C, \Pi_{\mathcal{V}} \setminus \Pi_{\mathcal{V}})$ with respect to φ ?

We study CCAV and CCDV in k -CP/axes elections. This means that for CCAV, $(C, \Pi_{\mathcal{V}} \cup \Pi_{\mathcal{W}})$ in the input is a k -CP/axes election, and for CCDV, $(C, \Pi_{\mathcal{V}})$ in the input is a k -CP/axes election.

2 OUR CONTRIBUTION

The complexity of CCAV and CCDV in general elections was initially studied by Bartholdi III, Tovey, and Trick [1]. Since then, the

Proc. of the 17th International Conference on Autonomous Agents and Multiagent Systems (AAMAS 2018), M. Dastani, G. Sukthankar, E. André, S. Koenig (eds.), July 10–15, 2018, Stockholm, Sweden. © 2018 International Foundation for Autonomous Agents and Multiagent Systems (www.ifaamas.org). All rights reserved.

	CCAV				CCDV			
	SP	$(k \geq 2)$ -axes	$(k \geq 2)$ -CP	general	SP	$(k \geq 2)$ -axes	$(k \geq 2)$ -CP	general
r -Approval	P [12]	FPT	$k = 2$: P [24] $k \geq 3, r \geq 4$: NP-h	$r \leq 3$: P [15] $r \geq 4$: NP-h [15]	P [12]	$r \leq 2$: P [15] $r \geq 3$: Open	$r \leq 2$: P [15] $r \geq 3$: NP-h	$r \leq 2$: P [15] $r \geq 3$: NP-h [15]
Borda		NP-h [21]		NP-h [19]		NP-h [21]		NP-h [17]
Condorcet	P [3]	FPT	$k = 2$: Open $k \geq 3$: NP-h	NP-h [1]	P [3]	FPT	$k = 2$: Open $k \geq 3$: NP-h	NP-h [1]
Copeland ^{$\alpha \in (0,1)$}	Open	NP-h	NP-h [22]	NP-h [11]	Open	NP-h	NP-h [22]	NP-h [11]
Copeland ¹	P [3]		NP-h	NP-h [11]	P [3]		NP-h	NP-h [11]
Maximin	P [3]		NP-h	NP-h [10]	P [3]		NP-h	NP-h [10]

Table 1: Complexity of CCAV and CCDV. Here, “P” stands for “polynomial-time solvable”, “NP-h” for “NP-hard”, and “SP” for “single-peaked”. Our results are in boldface. FPT results are with respect to k . The FPT results for Condorcet hold only when k axes of the given election are given, while the FPT result for r -approval holds even without knowing the k -axes in advance.

complexity of CCAV and CCDV for a number of voting correspondences has been investigated (see [13] for a survey). It is known that in general elections CCAV and CCDV for Borda, Condorcet, Maximin and Copeland ^{α} are NP-hard [1, 10, 11, 16]. Lin [15] derived dichotomy results for r -approval with respect to the values of r : CCAV is NP-hard iff $r \geq 4$, and CCDV is NP-hard iff $r \geq 3$. In contrast, when restricted to single-peaked elections, CCAV and CCDV for all aforementioned voting correspondences, except Borda and Copeland ^{α} where $0 \leq \alpha < 1$, are polynomial-time solvable [3, 12]. CCAV and CCDV for Borda in single-peaked elections were recently shown to be NP-hard by Yang [21]. To the best of our knowledge, the complexity of CCAV and CCDV for Copeland ^{α} for $0 \leq \alpha < 1$ still remains open so far.

Yang and Guo [22–24] studied CCAV and CCDV in elections with single-peaked width k and k -peaked elections. Generally, an election has *single-peaked width* k if the candidates can be divided into groups, each of size at most k , such that every vote ranks all candidates in each group consecutively and, moreover, considering each group as a single candidate results in a single-peaked election. An election is *k -peaked* if there is an axis \triangleleft such that for every vote π there is a k -partition of \triangleleft such that π restricted to each component of the partition is single-peaked. Yang and Guo [22] proved that CCAV and CCDV for Copeland ^{α} , where $0 \leq \alpha < 1$, in elections with single-peaked width k are NP-hard for every $k \geq 2$. Erdélyi, Lackner, and Pfandler [8] proved that every election with single-peaked width k is a k' -CP election for some $k' \leq k$. It then follows that CCAV and CCDV for Copeland ^{α} , where $0 \leq \alpha < 1$, are NP-hard in k -CP elections for every $k \geq 2$. For Copeland¹ and Maximin, Yang and Guo [22] proved that CCAV and CCDV in elections with single-peaked k is polynomial-time solvable if $k = 2$, but become NP-hard for every $k \geq 3$. Then, from the relation between nearly single-peaked elections studied in [8], it follows that CCAV and CCDV for Copeland¹ and Maximin are NP-hard in k -CP elections for every $k \geq 3$. We complete the final gap by showing that CCAV and CCDV for Copeland¹ and Maximin remain NP-hard in 2-CP elections. For Condorcet, Yang and Guo [22] proved that CCAV and CCDV are fixed-parameter tractable (FPT) with respect to the single-peaked width. In contrast, we show that the problems are NP-hard in k -CP elections for every $k \geq 3$. Concerning k -peaked elections, Yang and Guo [23] obtained the following results: for Condorcet, Maximin and Copeland ^{α} , where $0 \leq \alpha \leq 1$, CCAV is NP-hard in

3-peaked elections and CCDV is NP-hard in 4-peaked elections¹. As k -CP elections are a special case of k -peaked elections, our study fills several gaps left in [23] and shows NP-hardness results for even special cases of 2-peaked elections.

Yang and Guo [24] also derived dichotomy results for CCAV and CCDV for r -approval in k -peaked elections, with respect to the values of k and r . Particularly, they showed that CCAV for r -approval in 2-peaked elections is polynomial-time solvable if r is a constant, but becomes NP-hard if r is not a constant. As 2-CP elections are 2-peaked elections, their polynomial-time algorithm applies to CCAV for r -approval in 2-CP elections for all constants r . In addition, they proved that CCAV for r -approval in k -peaked elections for $k \geq 3$ and $r \geq 4$ is NP-hard. We strengthen this result by showing that the problem is NP-hard in k -CP elections for every $k \geq 3$ and $r \geq 4$. Moreover, Yang and Guo proved that CCDV for r -approval in 2-peaked elections is NP-hard iff $r \geq 3$. We strengthen their result by showing that CCDV for r -approval remains NP-hard in k -CP elections for every $r \geq 3$ and $k \geq 2$.

In addition, we study CCAV and CCDV in k -axes elections. We prove that CCAV for r -approval and Condorcet, and CCDV for Condorcet are FPT with respect to k . However, CCAV and CCDV for Maximin and Copeland ^{α} , $0 \leq \alpha \leq 1$, turn out to be NP-hard for every $k \geq 2$ and $0 \leq \alpha \leq 1$.

Table 1 summarizes our results and some related previous results.

Finally, we study the complexity of determining whether an election is a k -axes election. It is known that for $k = 1$, the problem is polynomial-time solvable [2, 7, 9]. Erdélyi, Lackner, and Pfandler [8] proved that the problem is NP-hard for every $k \geq 3$. We complement these results by showing that determining whether an election is a 2-axes election is polynomial-time solvable, filling the last complexity gap of the problem with respect to k .

THEOREM 2.1. *Determining whether an election is a 2-axes election is polynomial-time solvable.*

Many other problems pertaining to voting in nearly single-peaked elections have also been studied in the literature, see, e.g., [4, 5, 20, 23, 26] and references therein for further details. Moreover, voting problems in other restricted elections such as single-crossing elections have also been investigated recently, see, e.g., [18].

¹Precisely, they achieved W[1]-hardness results with respect to the solution size.

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